

# An Adaptive Super-Resolution Image Reconstruction Algorithm Based on Image Blocks

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## Abstract

Recently there have been significant advances in image super-resolution, we embark from an method to learn an over-complete dictionary with  $K$ -SVD algorithm, adopted a two-layer dictionary learning method because of the reason of restriction of over-complete dictionary's size and the intrinsic sparsity of the algorithm, and introduced collaborative representation to replace the sparse representation in reconstruction phase of two-layer dictionary learning method. And combined with an image reconstruction algorithm based on singular value decomposition, proposed an adaptive super-resolution image reconstruction algorithm based on image blocks. The proposed algorithm take advantage of high arithmetic speed of adaptive two-layer dictionary learning method and high image reconstruction precision of image reconstruction with singular value decomposition by which adaptive choose different method to reconstruct image blocks. The experimental results show that the proposed algorithm can greatly decrease the image reconstruction time and barely reduce the reconstruction precision.

**Keywords:** super-resolution image reconstruction, sparse representation, two-layer dictionary learning, adaptive

## 1. Introduction

Single-image super-resolution(SR) is a popular branch of image reconstruction that focuses on the enhancement of image resolution to generate a visually pleasing high-resolution output image from a low-resolution input image. SR is an ill-posed problem because each low resolution(LR) pixel has to be mapped onto many high resolution(HR) pixels, depending on the desired up-sampling factor.

Example-based super-resolution methods have been an active research topic to recover high-frequency details with the help of a database consisting of co-occurrence examples from a training set of HR and LR image patches [1-4]. Recent achievements in sparse representation suggest that the linear relationships among high-dimension signals can be accurately recovered from their low-dimension projections [5]. Instead of working directly with the patch pairs sampled from high and low-resolution images, based on the assumption that for a given low-resolution patch, the sparse representation vector in the over-complete dictionary trained by low-resolution images is the same as the one of its corresponding high-resolution patch in the over-complete dictionary trained by high-resolution images, learn a compact representation for these patch pairs to capture the co-occurrence prior to improve the speed and the robustness significantly, achieving state-of-art performance [7]. However, due to the restriction of over-complete dictionary's size and the intrinsic sparsity of the algorithm, one limitation in recovering high-frequency details should be noticed. As the gap between the frequency spectrum of the corresponding HR image and that of the initial interpolation is showed that

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learning-based algorithm usually can't work well. To address above problem, a two-layer algorithm is proposed, in which details of high-frequency are estimated by a progressive way [8]. The scheme can be seen as a coarse-to-fine recovering process and better results can be expected. However, the method increased computational complexity as the same time. In this paper, we adopted collaborative representation to replace the sparse representation in reconstruction phase, thus we can compute a projection matrix with the dictionary trained offline, then project the low-resolution image patch to high-resolution image patch, which reduced computation greatly. An image reconstruction is introduced to make use of rank deficiency, which exploited the corresponding relation between the sparse and low rank after singular value decomposition to image [11]. The singular value decomposition of image matrix uses the property of low rank for image reconstruction to obtain a pleasing reconstructed result. However, it has high computational complexity.

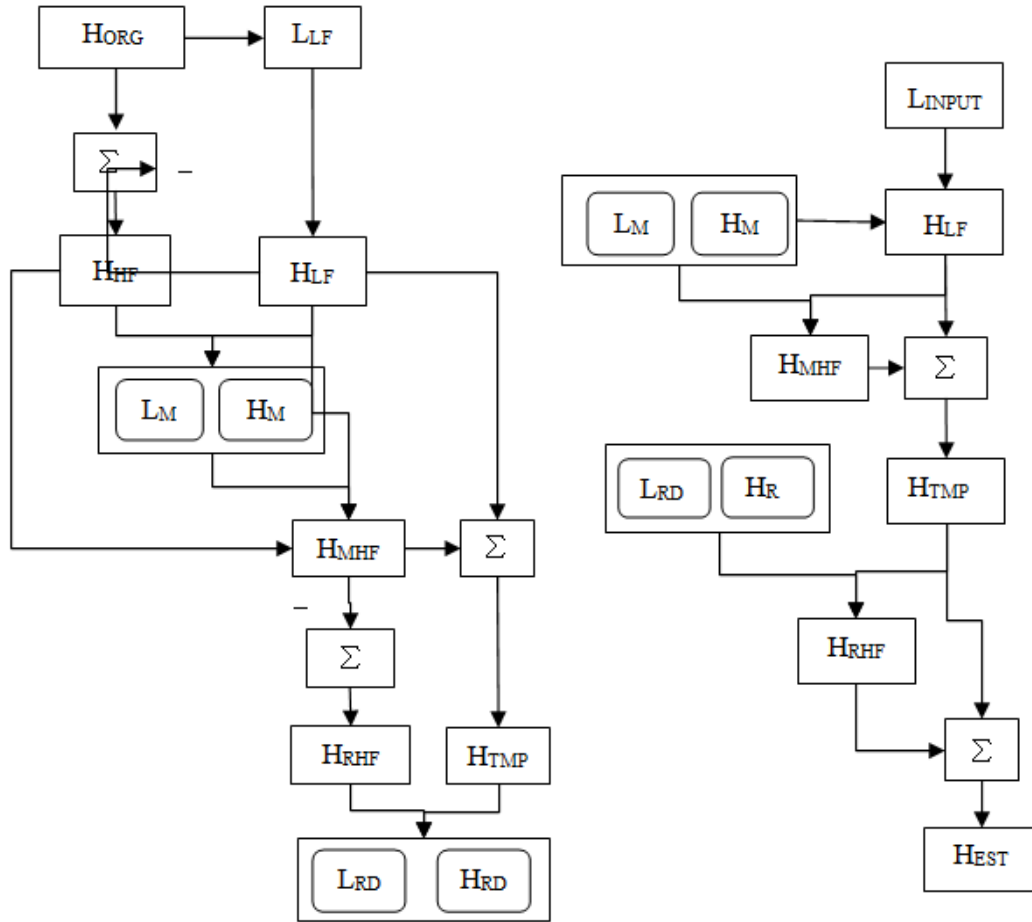
To make use of adaptive two-layer dictionary method's high executive speed and image reconstruction based on singular value decomposition method's high reconstruction precision, we proposed an adaptive of image reconstruction algorithm based on image blocks, which can choose the algorithm adaptively based on image block feature of variance to improve the speed of image super-resolution reconstruction.

In the following section we will described the two-layer dictionary learning method simply, which introduced collaborative representation to replace the sparse representation in reconstruction phase, and the image reconstruction algorithm based on singular value decomposition in Section 2. In Section 3, an adaptive image reconstruction algorithm is introduced and is explained in detail. All the experimental results in Section 4 and the conclusions are drawn in Section 5.

## **2. Dictionary-Based Super-Resolution Image Reconstruction**

### **2.1. Two-Layer Dictionary Super-Resolution Image Reconstruction**

The scheme also consists of a dictionary learning phase that trains dual dictionaries, namely main dictionary and residual dictionary and an image reconstruction phase, performing the image super-resolution on the input image using the trained model from the previous phase, as described in Figure 1.



**Figure 1. Process of Dictionary Learning and Process of Image Reconstruction**

### A. Dictionary Training

Firstly, collect a set of training HR images. As illustrated in Figure 1, a HR training image denoted by  $H_{ORG}$ , and a corresponding low-resolution image denoted by  $L_{LF}$  is constructed using blurred and down-sampled operator. The HR low-frequency image denoted by  $H_{LF}$  is generated by applying bicubic interpolation on  $L_{LF}$ , as the low-resolution image of the first dictionary training, which is of the same size as  $H_{org}$ . Then, by subtracting  $H_{LF}$  from  $H_{org}$ , HR high-frequency image  $H_{HF}$  is constructed as the high-resolution image of the first dictionary training. With the extraction of features from local patches of  $H_{LF}$  and  $H_{HF}$ , training data  $TD = \{p_h^k, p_l^k\}_k$  is constructed.  $p_h^k$  is the set of patches extracted from the high-resolution image directly, and  $p_l^k$  is the patches built by extracting patches from filtered images obtained by filtering image  $H_{LF}$  with certain high-pass filters as described in equation (1). Now, the dimension of low super-resolution image features vectors is 4 times larger than high-resolution image features vectors, so in order to reduce the complexity, reducing the dimensions by Principal Component Analysis (PCA) algorithm.

$$f_1 = [0, 0, 1, 0, 0, -1], \quad f_2 = f_1^T, \quad f_3 = [1, 0, 0, -2, 0, 0, 1], \quad f_4 = f_3^T \quad (1)$$

The main dictionary will be built by training the high-resolution images and

low-resolution images, which is consist of two sub-dictionaries: low-frequency main dictionary  $\mathbf{L}_{MD}$  and high-frequency main dictionary  $\mathbf{H}_{MD}$ . Firstly, the K-SVD dictionary training [8] is applied to the set of patches  $\{\mathbf{p}_l^k\}_k$ , generating  $\mathbf{L}_{MD}$ .

$$\mathbf{L}_{MD}, \{\mathbf{q}^k\} = \underset{\mathbf{L}_{MD}, \{\mathbf{q}^k\}}{\operatorname{argmin}} \sum_k \|\mathbf{p}_l^k - \mathbf{L}_{MD} \cdot \mathbf{q}^k\|_2^2 \quad s.t. \|\mathbf{q}^k\|_0 \leq L \quad \forall k \quad (2)$$

Where  $\{\mathbf{q}^k\}_k$  are sparse representation vectors, and  $\|\bullet\|_0$  is  $L_0$  norm counting the nonzero entries of a vector. Based on the assumption that the patch  $\mathbf{p}_h^k$  can be recovered by approximation as  $\mathbf{p}_h^k \approx \mathbf{H}_{MD} \cdot \mathbf{q}^k$ ,  $\mathbf{H}_{MD}$  can be defined by minimizing by following mean approximation error.

$$\mathbf{H}_{MD} = \underset{\mathbf{H}_{MD}}{\operatorname{argmin}} \sum_k \|\mathbf{p}_h^k - \mathbf{H}_{MD} \cdot \mathbf{q}^k\|_2^2 = \underset{\mathbf{H}_{MD}}{\operatorname{argmin}} \sum_k \|\mathbf{P}_h - \mathbf{H}_{MD} \cdot \mathbf{Q}\|_2^2 \quad (3)$$

Where the matrix  $\mathbf{P}_h$  and  $\mathbf{Q}$  is the set of  $\{\mathbf{p}_h^k\}_k$  and  $\{\mathbf{q}^k\}_k$  as its columns, respectively. The solution of the problem is given by the following Pseudo-Inverse expression (given that Q has full row rank):

$$\mathbf{H}_{MD} = \mathbf{P}_h \mathbf{Q}^+ = \mathbf{P}_h \mathbf{Q}^T (\mathbf{Q} \mathbf{Q}^T)^{-1} \quad (4)$$

Finally, the residual dictionary will be trained similar to the training process of main dictionary. The main high-frequency image denoted by  $\mathbf{H}_{MHF}$  is produced by the image reconstruction of HR low-frequency image  $\mathbf{H}_{LF}$  with the main dictionary. Then get the input image of residual dictionary learning with the summing of  $\mathbf{H}_{MHF}$  and  $\mathbf{H}_{LF}$  denoted by  $\mathbf{H}_{TMP}$ . As the  $\mathbf{H}_{TMP}$  which is the low-resolution image of the second dictionary learning stage contains more details than  $\mathbf{H}_{LF}$  which is the input image of the first dictionary learning stage, and the  $\mathbf{H}_{RHF}$  is the high-resolution image of the second dictionary learning stage which is deserved by subtracting  $\mathbf{H}_{MHF}$  from  $\mathbf{H}_{HF}$ , thus the precise of dictionary learning can be improved.

## B. Image Reconstruction

To begin with, a test low-resolution image is given by the same blur and down-sampled operator to original high-resolution image as in dictionary learning phase. Then it is interpolated to the size of original high-resolution image denoted by  $\mathbf{H}_{LF}$ . The image  $\mathbf{H}_{LF}$  is filtered by the filters as shown in equation (1) that were used for feature extraction in the training, and patches are extracted from these images which forms the set  $\{\mathbf{p}_l^k\}_k$ .

Combine the high-resolution low-frequency image  $\mathbf{H}_{LF}$  with the main dictionary MD, the first estimated high-resolution image denoted by  $\mathbf{H}_{MHF}$  is reconstructed with the following problem which is regularized using the  $L_1$ -norm of the coefficients[7].

1) The image  $\mathbf{H}_{LF}$  is filtered by the filters as shown in equation (1) that were used for feature extraction in the training, and patches are extracted from these images which forms the set  $\{\mathbf{p}_l^k\}_k$

2) combined patches  $\{\mathbf{p}_l^k\}_k$  with main dictionary, using OMP algorithm to find the sparse representation vectors  $\{\mathbf{q}^k\}_k$ .

3) the representation vectors  $\{\mathbf{q}^k\}_k$  are multiplied by  $\mathbf{H}_{MD}$ , the corresponding high-resolution patches  $\{\hat{\mathbf{p}}_h^k\}_k \approx \{\mathbf{H}_{MD} \cdot \mathbf{q}^k\}_k$ , are obtained.

Define the operator  $\mathbf{R}_k$ , which extracts a patch of size  $n \times n$  from the high-resolution image in location  $k$ . then the main high-frequency image denoted by  $\mathbf{H}_{MHF}$  can be calculated by

$$\mathbf{H}_{MHF} = \underset{\mathbf{H}_{MD}}{\operatorname{argmin}} \sum_k \left\| \mathbf{R}_k \mathbf{H}_{MHF} - \hat{\mathbf{p}}_h^k \right\|_2^2 \quad (5)$$

This problem has a closed-form Least-Squares solution, given by

$$\mathbf{H}_{MHF} = \left[ \sum_k \mathbf{R}_k^T \mathbf{R}_k \right]^{-1} \sum_k \mathbf{R}_k^T \hat{\mathbf{p}}_h^k \quad (6)$$

Then take the  $\mathbf{H}_{MHF}$  as input and reconstructed the final high-resolution image with the same method.

## 2.2. Collaborative Representation

As shown in above method, usually regularized the reconstruction problem using the  $L_1$ -norm of the coefficients, which is computationally demanding. We can reformulate the problem as a least squares regression regularized by the  $L_2$ -norm of the coefficients. Thus, we use Collaborative representation and have a closed-form solution. The problem becomes

$$\min_{\alpha} \left\{ \left\| \mathbf{H}_{LF} - \mathbf{L}_{MD} \alpha \right\|_2^2 + \lambda \left\| \alpha \right\|_2 \right\} \quad (7)$$

where  $\mathbf{L}_{MD}$  is the low-resolution dictionary and the parameter  $\lambda$  allows us to alleviate the ill-posed problems and stabilized the solution, which is the coefficients vector. The algebraic solution is given by

$$\alpha = (\mathbf{L}_{MD}^T \mathbf{L}_{MD} + \lambda \mathbf{I})^{-1} \mathbf{L}_{MD}^T \mathbf{H}_{LF} \quad (8)$$

Then the high-resolution patches can be computed using the same coefficients on the high resolution dictionary  $\mathbf{H}_{MD}$

$$\mathbf{x} = \mathbf{H}_{MD} \alpha \quad (9)$$

where  $\mathbf{x}$  is the HR output patch and  $\mathbf{H}_{MD}$  the HR dictionary corresponding to  $\mathbf{L}_{MD}$ . From the equation (8) and equation (9), we obtain

$$\mathbf{x} = \mathbf{H}_{MD} (\mathbf{L}_{MD}^T \mathbf{L}_{MD} + \lambda \mathbf{I})^{-1} \mathbf{L}_{MD}^T \mathbf{H}_{LF} \quad (10)$$

$$\mathbf{P}_G = \mathbf{H}_{MD} (\mathbf{L}_{MD}^T \mathbf{L}_{MD} + \lambda \mathbf{I})^{-1} \mathbf{L}_{MD}^T \quad (11)$$

where  $\mathbf{P}_G$  is a projection matrix can be computed offline. This means that we only need to multiply the pre-computed projection matrix  $\mathbf{P}_G$  with the LR input feature

vector,  $L_{MD}$ , to calculate the HR output patches  $X$ . This can be reduced the computation and complexity greatly during the SR reconstruction algorithm.

At last, the final estimated high-resolution image is constructed with residual dictionary by the same method to the reconstruction with main dictionary. And the input image is the reconstruction image in the first reconstruction phase. We named this algorithm TDL-CR (Two-Layer Dictionary Learning method with Collaborative Representation, TDL-CR).

### 2.3. Image Reconstruction Based on Svd

Owing to the spatial redundancy, many images do not have full rank. Singular Value Decomposition(SVD) as the important method of matrix decomposition, to compressed large data using the properties of rank deficient of images. For an image  $x$ , can be expressed as a matrix, it can be defined as the SVD problem.

$$X = US_X V' \quad (12)$$

where both  $U$  and  $V$  are orthonormal matrices and  $S_X$  is a diagonal matrix. Equation (12) can also be transformed to a problem of minimize the rank of an reconstruction image.

$$\text{minimize: } \text{rank}(X) \quad \text{s.t.} \|y - Fx\|_2 < \varepsilon \quad (13)$$

where  $F$  is the blur and subsampled operator. Equation (13) can be reformulated to equation (14).

$$\min \|X\|_* \quad \text{s.t.} \|y - Fx\|_2 \leq \varepsilon \quad (14)$$

where  $\|X\|_*$  is nuclear norm of  $X$ , defined as sum of singular values. Usually,  $l_p$  is a better approximation of the matrix rank than nuclear norm  $l_1$ , so we use  $l_p$  to replace  $l_1$ .

$$\min \|X\|_p, 0 < p < 1 \quad \text{s.t.} \|y - Fx\|_2 \leq \varepsilon \quad (15)$$

where  $\|X\|_{p^*} = \sum \sigma_i^p$ .

The problem is to solve (14). However, it is difficult to solve the constrained problem directly. Therefore we propose to solve the following unconstrained Lagrange version of (14) which is easier to solve

$$J(x) = \min \|y - Fx\|_2 + \lambda \|X\|_p \quad (16)$$

### 3. Proposed Methods

Compared with the two-layer dictionary learning method with Collaborative Representation algorithm, the iterative algorithm based on SVD provides more image details with improved PSNR, but the iterative algorithm demand much computation and complexity, thus need much more time to reconstruct image. So we propose an adaptive super-resolution image reconstruction algorithm based on image blocks.

First, divide the image and compute every image block's variance, then classification according to the variance for image blocks of an image, if the variance of image block less than the set threshold, then reconstruct the image area of smoothing and gray changes

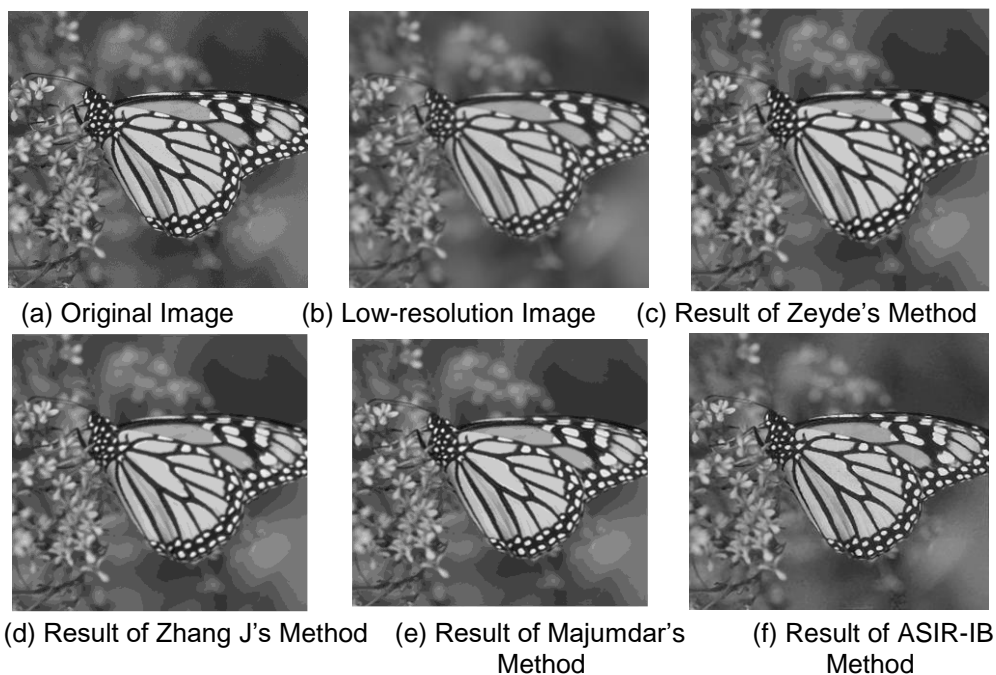
slowly with TDL-CR algorithm, otherwise judgment the image block be the relatively complex block structure, has rich details and reconstruct it with iterative algorithm based on SVD. And then combine all the reconstructed high-resolution image blocks. The global reconstruction constraint enforced by iterative back-projection method to optimization the reconstructed high-resolution image. As we take advantage of TDL-CR method which have the high arithmetic speed, and image reconstruction method of singular value decomposition which have the high precision of image reconstruction, the proposed method can reduced the reconstruction time greatly and barely reduced reconstruction precision.

#### 4. Experimental Results

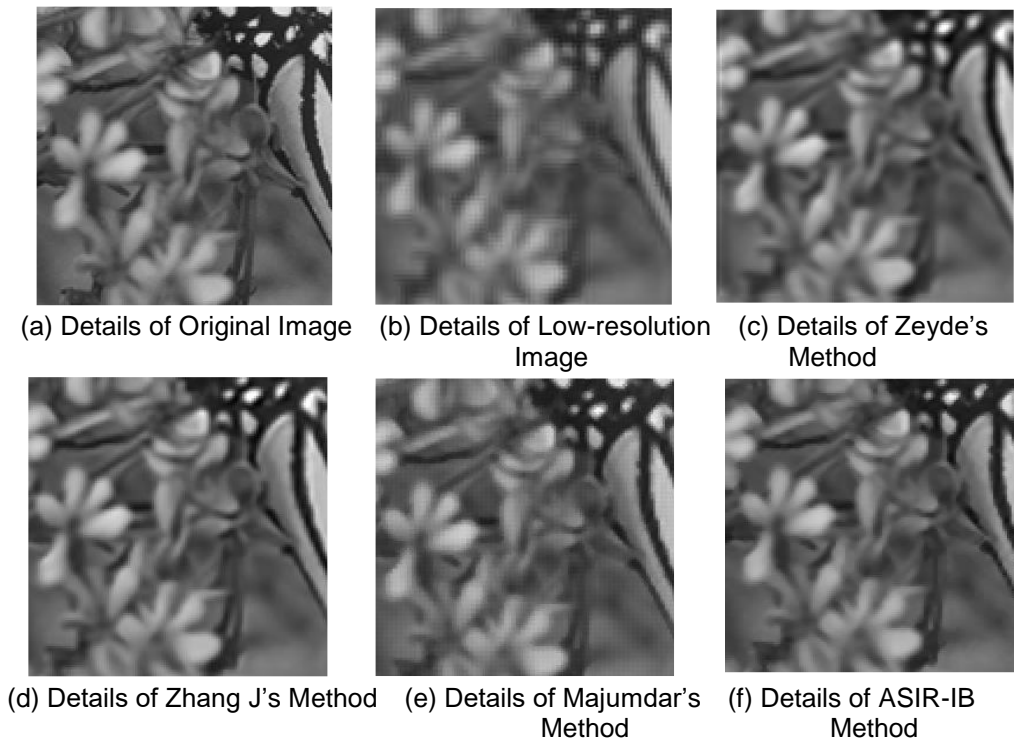
In this section, we first demonstrate the SR results obtained by applying different methods on generic images to identify the effects of our algorithm. We then moved on to discuss various influential factors for the proposed algorithm including the set variance threshold, the size of image block size, size of image patch and different magnify factors.

In our experiments, we magnify the input low-resolution image by a factor of 2 for generic images. We implement our method on some test images to compare with other interpolation methods, the training parameters set as the following.

The blurring operator is  $7 \times 7$  Gaussian filter with standard deviation of 0.9, the size of MD and the size of RD are both set to 500. The size of image patch is  $9 \times 9$  with overlap of 3 pixel. The PSNR and time consuming comparing with different methods are listed in Table 1. It can be seen from Table 1 that the proposed method achieves faster time than reference [11] and have the PSNR slightly less than [11]. For up-scaling factor 2, our proposed algorithm is 3 times faster than reference [11]. Due to the image information statics, most of image information are smooth and low-frequency information, high-frequency information and details are only accounts for a small part of image, as the image be partitioned, most smooth area using the two-layer dictionary method to reconstructed high-resolution image block, which greatly reducing image reconstruction time. The visual reconstruction results with different method are presented in Figure 2 and the details of test images are shown as Figure 3.



**Figure 2. Reconstructed Images of Monarch**



**Figure 3. Details of Reconstructed Images of Monarch**

**Table 1. Comparison of Time Consuming and PSNR for Four Methods**

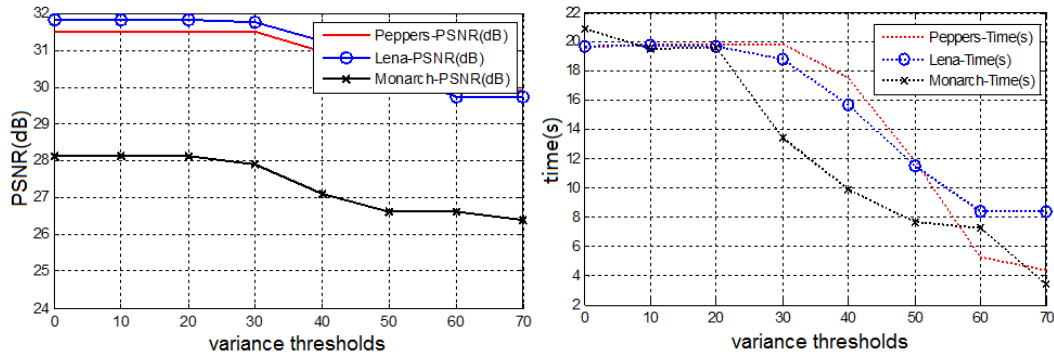
Method	Zeyde		Zhang J		Majumdar		ASIR-IB	
	PSNR (dB)	Time (s)	PSNR (dB)	Time (s)	PSNR (dB)	Time (s)	PSNR (dB)	Time (s)
Monarch	26.38	3.90	26.73	12.64	28.14	41.82	27.90	14.91
Peppers	30.60	4.13	31.53	12.44	32.51	45.89	31.50	17.00
Lena	29.88	4.20	29.97	12.76	32.23	47.50	31.77	13.44
Cameraman	23.58	1.01	23.78	3.14	24.94	9.01	24.27	5.33
Plane	29.02	4.34	29.23	13.32	31.21	48.72	30.70	14.94
House	29.41	1.06	29.46	3.35	31.48	9.21	30.23	3.17
Average	28.15	3.11	28.45	9.61	30.09	33.69	29.40	11.47

#### 4.1. Effect of the Set Variance Threshold

The previously mentioned experimental results show that the effective of our method to speed up reconstruction process. In those results, we fix the threshold  $\sigma$  to be 35. Intuitively, if the threshold  $\sigma$  to be 0, that means the high-resolution images are obtained by reconstruction algorithm of based on SVD. With the increase of threshold  $\sigma$ , more low-resolution image blocks reconstruct corresponding high-resolution image blocks with two-layer dictionary learning with TDL-CR algorithm, that will lead to the PSNR of the reconstruction image will be decrease, and the speed of reconstruction will be accelerated. Figure 5 shows the PSNR of reconstructed results and the computation time in seconds for test images. We can see that when the threshold  $\sigma$  is 30, the PSNR of reconstructed results will decrease slowly, while the computation time of reconstructed



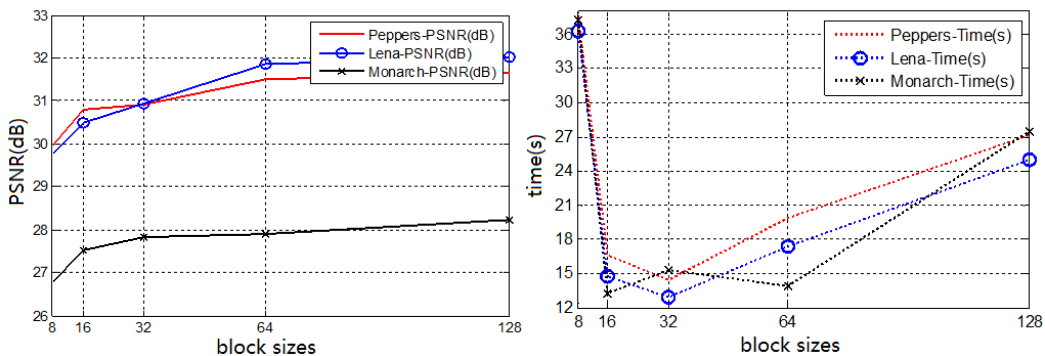
will decrease fast at 30 and slowly steady at 50, so we set the threshold  $\sigma$  is 30–50.



**Figure 4. PSNR and Time-Consuming of Reconstructed Results for Different Variance Thresholds**

#### 4.2. Effect of Image Block Size

The algorithm need to divided into some blocks thus can adaptive choose different algorithm to reconstructed corresponding high-resolution blocks. While the block size is too small, much blocks need to be reconstructed, thus will lead to too much consuming time to obtain the high-resolution image. In order to analysis the influence of image block size on reconstruction results, we have designed experiments to test the performance of image reconstruction algorithm on different image block size. Figure 6 shows the PSNR of reconstructed results and the computation time in seconds with test images. It can be seen that the PSNR of reconstructed image improved with the increase of block size and steady at block size is  $64 \times 64$ , while less time of image reconstruction needed when block size is  $16 \times 16$ ,  $32 \times 32$  and  $64 \times 64$ . We set the block size  $64 \times 64$  or  $32 \times 32$  to get the better performance of our algorithm.

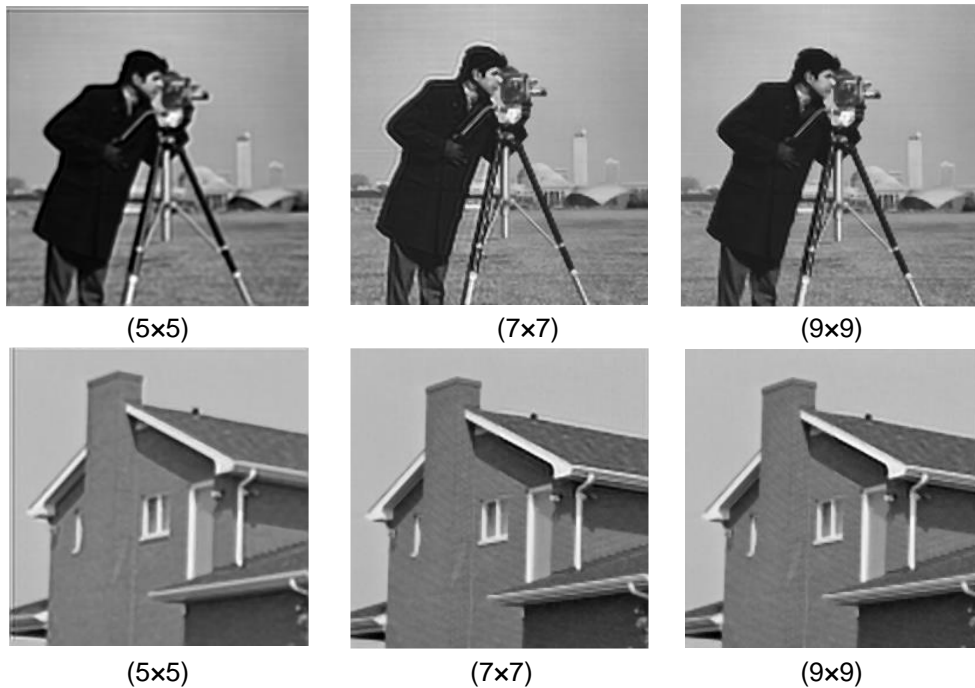


**Figure 5. PSNR and Time-Consuming of Constructed Results for Different Block Sizes**

#### 4.3. Effect of Image Patch Size in Dictionary Learning

Another important issue of the proposed method is the size of image patch in process of TDL-CR algorithm. Obviously, the patch size cannot be big, otherwise, they will not be micro-structures and hence cannot be represented by a small number of atoms. To evaluate the effects of the patch size on image reconstructed results, we trained the two couple dictionaries and reconstructed high-resolution images with different patch size,  $5 \times 5$ ,  $7 \times 7$  and  $9 \times 9$ . Then we applied the two couple dictionaries to the test images. The experimental results of super-resolution are presented in Figure 7, from which we can see that the smaller patch sizes tend to generate some artifacts in smooth regions. Therefore,

we adopt  $9 \times 9$  as the image patch size in the dictionary learning and reconstruction of our algorithm.



**Figure 6. Reconstructed Results of Different Patch Sizes in Dictionary Training Method**

#### 4.4. Different Magnifications

To more comprehensively test the adaptability to high-resolution image reconstruction of the proposed image reconstruction method, we performed different up-scaling factors on test images, as shown in Figure 8. The performance in terms of PSNR and running time are shown at Table 2. The larger up-scaling factor tend to lower PSNR and running time, but the proposed method still have better visual reconstructed results, as shown in Figure 9.



**Figure 7. Low-Resolution Image at Different Magnifications**



**Figure 8. Results of Image Super-resolution Reconstruction at different Magnifications**

**Table 2. PSNR and Time Consuming for Reconstruction at Different Magnifications**

Magnification	2		3		4	
Test image	PSNR(dB)	Time(s)	PSNR(dB)	Time(s)	PSNR(dB)	Time(s)
Boats	30.16	6.01	24.75	5.31	23.20	4.65
Barbara	27.41	6.32	23.08	5.43	21.64	4.47

## 5. Conclusions

We proposed an adaptive of image reconstruction method based on image blocks. We also introduced collaborative representation to replace the sparse representation in reconstruction phase of two-layer dictionary learning method, which focuses purely on high arithmetic speed in exchange for some visual quality loss. We combined the advantage of TDL-CR method which have the high arithmetic speed, and image reconstruction method of singular value decomposition which have the high precision of image reconstruction, the proposed adaptive of image reconstruction method can greatly decrease the image reconstruction time and barely reduce the reconstruction precision.

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