

One Rank Cuckoo Search Algorithm for Bi-Objective Load Dispatch Problem

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Abstract

This paper presents the application of a One Rank Cuckoo Search Algorithm (ORCSA) to bi-objective load dispatch (BOLD) problem where two objectives including fuel and emission are taken into consideration. ORCSA is an improvement of basic Cuckoo search algorithm (BCSA) where several modifications are carried out so as to improve the performance of the BCSA. The performance of the proposed ORCSA is validated by using two systems including a three-unit system with one load case and a six-unit system with three load cases and comparing the obtained results with other methods available in the article. The analysis on the result comparison indicates that the ORCSA is very efficient for the problem.

Keywords: One Rank Cuckoo Search algorithm, bi-objective, load dispatch, fuel cost, emission.

Nomenclature

F_{1i}	Fuel Cost function of thermal unit i in \$/h
F_{2i}	Emission function of thermal unit i in kg/h
w_1, w_2	Weights corresponding to the fuel cost and emission objectives.
a_i, b_i, c_i	Cost coefficients of thermal unit i
d_i, e_i, f_i	Emission coefficients of thermal unit i
N	Number of thermal units
P_D	Load demand of the system in MW
P_L	Total network loss of the system in MW
P_i	Power output of unit i in MW
B_{ij}, B_{0i}, B_{00}	Transmission loss formula coefficients
P_{imin}, P_{imax}	Lower and upper generation limits of unit i in MW
$rand$	Uniformly distributed random number in $[0, 1]$
P_{1d}	Power output of the slack thermal unit 1 of nest d in MW
P_{1max}, P_{1min}	Maximum and minimum power outputs of slack thermal unit 1 in MW
P_s^{lim}	Limit for the slack unit 1 in MW
F_j	Value of objective j
F_{jmax}, F_{jmin}	Maximum and minimum values of objective j .
μ_D^k	Cardinal priority of k th non-dominated solution

$\mu(F_i^k)$	Membership function of objective j
N_{obj}	Number of objective functions
N_S	Number of Pareto-optimal solutions.
μ_D^k	Membership function

1. Introduction

Bi-objective load dispatch is a very important problem in power system since both electricity generation fuel cost and emission produced from the electricity generation process are minimized in addition to satisfying all thermal unit constraints such as maximum and minimum limits on power output.

Recent decades, many methods, which based on deterministic algorithms and meta-heuristic algorithms, have been widely and successfully applied for solving the BOLD problem such as lambda-iteration method [1], Hopfield Lagrange Network (HNN) [1], Improved Hopfield Neural Network Model (IHNN) [2], Tabu Search (TS) [3], fuzzy logic controlled genetic algorithm (FCGA) [4], the Non-dominated Sorting Genetic Algorithm - II (NSGA-II) [5], Differential Evolution (DE) [6], biogeography-based optimization (BBO) [7], multi-objective differential evolution (MODE) [8], Hybrid Differential evolution-sequential quadratic programming (DE-SQP) and Hybrid Particle Swarm optimization- sequential quadratic programming (PSO-SQP) [9], parallel synchronous PSO algorithm (PSPSO) [10], Basic Cuckoo Search Algorithm (BCSA) [11].

Among the methods, Lamda-iteration and HNN are ones based on the Lagrange optimization function where the comer is mainly dependent on the initial value of lamda that is predetermined and the increased value of lamda whereas the later must suffer difficulty of determining control parameters. It is stated from the study [1] that the application of the methods is easy due to the simple implementation for the problem. The IHNN copes with the local optimization with high number of iteration for convergence and long execution time. The mentioned methods have the same characteristic that they can not deal with the problem where nonconvex objective function is considered. On the contrary, methods belonging to meta-heuristic algorithms such as DE, MODE, PSPSO and CSA, *etc.* can tackle the drawback since they simply obtain optimal solution for large scale system with nonconvex objective function. The difference between DE and MODE is that MODE can determine the best compromise solution, which can satisfy both cost and emission minimization requirement without using fuzzy mechanism like DE. The advantage allows MODE to reduce the computing procedure and execution time as well.

Recent years, the methods formed by combining two original algorithms have widely been developed for solving BOLD problem such as DE-SQP and PSO-SQP. The advantage of the methods is that they can take advantage of each individual to enhance the solution approaching the global optimization; however, the methods have to cope with the selection of higher number of control parameters and longer execution time.

In this paper, a One Rank Cuckoo Search Algorithm (ORCSA), developed by Ahmed in 2013, is proposed for solving the bi-objective load dispatch problem where two objectives including fuel and emission, and limits on power output are taken into consideration. The performance of the ORCSA has been validated by testing on different systems and compared to other methods consisting of Tabu Search (TS) [3], FCGA [4] and CGA [4], [NSGA-II [5], BBO [7], and CSA [11].

2. Problem Formulation.

The objective of the BOLD problem is to minimize both fuel cost and emission as expressed in eq. (1) below.

$$\text{Min} \sum_{i=1}^N (w_1 F_{1i}(P_i) + w_2 F_{2i}(P_i)) \quad (1)$$

Where F_{1i} and F_{2i} are respectively the fuel cost function and emission function of thermal unit i . The emission is approximately represented as a quadratic function and the fuel cost is also depicted as a second order equation due to neglecting valve-point loading effects. The two functions are shown in detail as the following equations.

$$F_{1i} = c_i P_i^2 + b_i P_i + a_i \quad (2)$$

$$F_{2i} = f_i P_i^2 + e_i P_i + d_i \quad (3)$$

On the other hands, all variables in eq. (1) must satisfy all the equality and inequality constraints below.

1. Real Power balance constraints: the total power generated by all thermal units must be equal to the sum of load demand and transmission losses.

$$\sum_{i=1}^N P_i - P_L - P_D = 0 \quad (4)$$

Where the transmission line power losses P_L is determined by:

$$P_L = \sum_{i=1}^{N_1} \sum_{j=1}^{N_1} P_i B_{ij} P_j + \sum_{i=1}^N B_{0i} P_i + B_{00} \quad (5)$$

2. Generator operating limits: power output of thermal unit must be in feasible operating zone.

$$P_{i\min} \leq P_i \leq P_{i\max} \quad (6)$$

3. Weight constraint [13]: the sum of weight factors associated to fuel cost function and emission function is equal to one.

$$w_1 + w_2 = 1 \quad (7)$$

Note that the value of the weight factors decides if the economic dispatch, emission dispatch or bi-objective load dispatch are carried out. The economic dispatch is performed since the w_1 and w_2 are set to 1 and 0 whereas the emission dispatch is carried out once the w_1 and w_2 are set to 0 and 1. For bi-objective load dispatch, a set of non-dominated solutions is determined by set w_1 and w_2 to the range from 0 to 1 so that their sum is exactly equal to one. A fuzzy mechanism is then applied to determine the best compromise solution, which is the optimal solution for the bi-objective load dispatch.

3. One Rank Cuckoo Search Algorithm for BOLD Problem.

3.1. One Rank Cuckoo Search Algorithm

In BCSA method [11], new eggs are generated two times including via Lévy Flights and via the replacement of a fraction of eggs. The new eggs obtained by the comer are

evaluated before being replaced in the later and the eggs in the later are evaluated and ranked. In the ORCSA, the first new solutions via Lévy flights are replaced and finally evaluated and ranked at once. This manner allows ORCSA to reduce the step of fitness evaluation by combining new eggs from via Lévy Flights and via the replacement of a fraction of eggs together before evaluating their fitness function.

One more parameter introduced in ORCSA is to decide if the computational process merges the two new solution generations together, called one rank ratio r_{or} . At the beginning, it is set to 1 to allow combing all new eggs from the first and second generation. This ratio is still fixed at 1 until there is no a better egg found out at the current iteration. For this case, the ratio value is set to lower value by the following rule.

$$r_{or}^{G+1} = r_{or}^G - 0.5 / N \quad (8)$$

Where G is the current iteration and N is the number of thermal units.

3.2. Implementation of One rank Cuckoo Search Algorithm for BOLD Problem

The main steps for the proposed ORCSA for solving BOLD problem are described as follows:

1) *Initialization*: Similar to BCSA, in the ORCSA each cuckoo nest in the all initial nests N_p is represented by a vector $X_d = [P_{d2}, \dots, P_{dN}]$ ($d = 1, \dots, N_p$). The maximum and minimum values of each nest are respectively $X_{min}=[P_{imin}]$ and $X_{max}=[P_{imax}]$. Consequently, each nest X_d is randomly initialized within the limits $X_{min} \leq X_d \leq X_{max}$ ($i=2, \dots, N$) as follows.

$$X_d = X_{dmin} + rand * (X_{dmax} - X_{dmin}) \quad (9)$$

The power output of from thermal unit 2 to thermal unit N is available in each nest, the thermal unit 1 P_{d1} for each nest d is then obtained by using the eq. (4) and (5).

$$P_{1d} = \sum_{i=2}^N P_{id} - P_L - P_D \quad (10)$$

Fitness function is calculated to evaluate the quality of each solution. The value includes objective function value and the penalty value of the slack thermal unit 1. The detail of fitness function is as below.

$$FT_d = \sum_{i=1}^N (w_1 F_{1i}(P_{id}) + w_2 F_{2i}(P_{id})) + K_s (P_{1d} - P_{1d}^{lim})^2 \quad (11)$$

Where the limit in (11) is obtained by:

$$P_{1d}^{lim} = \begin{cases} P_{1max} & \text{if } P_{1d} > P_{1max} \\ P_{1min} & \text{if } P_{1d} < P_{1min} \\ P_{1d} & \text{otherwise} \end{cases} \quad (12)$$

The initial population of the host nests is set to best value of each nest X_{best_d} ($d = 1, \dots, N_d$) and the nest corresponding to the best fitness function in (11) is set to the best nest G_{best} among all nests in the population.

2) *The first new solution generation via Lévy flights*

In this section, the first new solution is carried out by using Lévy flights by Mantegna's algorithm. The new solution by each nest is calculated as follows:

$$X_d^{new} = X_{best_d} + \alpha \times rand \times \Delta X_d^{new} \quad (13)$$

where $\alpha > 0$ is the updated step size and the increased value ΔX_d^{new} is determined as

described in [11] .

3) Bound by best solution for handling violated solutions

All new solutions obtained by *Lévy flights* must be a feasible satisfying not only power balance constraint (4) but also minimum and maximum limits (6). Normally, as a solution violates their limits, the normal method is to set it to the maximum value in case of the maximum value violated or to minimum value if the solution is lower than minimum limit. However, a bound by best solution mechanism is first introduced in ORCSA to deal with the violation of the limits. A thermal unit in a nest is either replaced with a corresponding valid one from a randomly selected nest or randomly reinitialized in range of minimum and maximum limits. To decide the way for handling the violation, a bound by best ratio r_{bbb} is defined as follows:

$$r_{bbb} = 1 - 1/\sqrt{D} \quad (14)$$

If $P_{i,d}$ from nest d is out of its limits, a random number rd is randomly generated in range $[0, 1]$ and the task for dealing with issue is as below.

- *Case 1:* $P_{i,d}$ is initialized randomly as eq. (8) if random number rd is less than r_{bbb} .
- *Case 2:* $P_{i,d}$ is replaced with $P_{i,r}$ from nest X_r (X_r is a randomly chosen nest where $P_{i,r}$ is a feasible value) if the random number rd is equal to or higher than r_{bbb} .

4) The second new solution generation via the discovery of alien egg:

In the section, only a fraction of current solutions above is newly generated using the probability Pa as the following equation.

$$X_d^{new} = \begin{cases} X_d + rand_{rand_8} \times [rand_{p_1}(X_{best_d}) - rand_{p_2}(X_{best_d})] & \text{if } rand < Pa \\ X_d & \text{otherwise} \end{cases} \quad (15)$$

3.3. Overall Iterative Algorithm

The overall procedure of the proposed ORCSA for solving the BOLD problem is described as follows.

- Step 1: Select values for control parameters N_p , G_{max} and P_a .
- Step 2: Initialize a population of host nests as in eq. (9) and calculate the slack unit using eq. (10).
- Step 3: Calculate fitness function (11) to set all nests to X_{best} and the best nest with the lowest value of fitness function to G_{best} . Set one rank ratio $r_{or} = 1$ and the iteration counter $G = 1$.
- Step 4: Generate new solutions via *Lévy flights* as in Section 3.2.2.
- Step 5: Generate a random number rd and compare to the one rank ratio r_{or} . If the random number is higher than r_{or} , go to Step 9.
- Step 6: Generate new solution via discovery of alien eggs as in Section 3.2.4.
- Step 7: Use bound by best solution mechanism to fix invalid solutions as in Section 3.2.3
- Step 8: Calculate slack unit 1 and the fitness function, then rank and keep the current best nest. Go to Step 14.
- Step 9: Perform bound by best solution mechanism to determine a new solution.
- Step 10: Calculate slack unit 1 and the fitness function, then rank and keep the current best nest.
- Step 11: Discover alien eggs and randomize to generate a new solution.
- Step 12: Use bound by best solution mechanism to fix invalid solutions as in Section 3.2.3

- Step 13: Calculate slack unit 1, obtain fitness function, then rank and keep the current best nest.
 Step 14: Store the best nest G_{best} for the current iteration.
 Step 15: If the current best nest G_{best} is not better than that of the previous iteration, obtain the new value of the one rank ratio using (8). Otherwise, retain the old value.
 Step 16: If the current iteration $G < G_{max}$, $G = G + 1$ and return to Step 4. Otherwise, stop the procedure.

4. Best Compromise Solution by Fuzzy-Based Mechanism

In the economic emission load dispatch, there is a difficulty to determine a solution which has acceptable fuel cost and emission values. In fact, as an optimal was solution found out it can certainly satisfy a particular objective due to its simple fitness function. Therefore, there is a set of non-dominated solutions first found and then the compromise one is determined based on the fuzzy satisfying method [14]. The linear membership function of the technique is as follows [14]:

$$\mu(F_j) = \begin{cases} 1 & \text{if } F_j \leq F_{j\min} \\ \frac{F_{j\max} - F_j}{F_{j\max} - F_{j\min}} & \text{if } F_{j\min} < F_j < F_{j\max} \\ 0 & \text{if } F_j \geq F_{j\max} \end{cases} \quad (16)$$

For each k non-dominated solution, the membership function is normalized as follows [13]:

$$\mu_D^k = \frac{\sum_{i=1}^{Nobj} \mu(F_i^k)}{\sum_{k=1}^{Np} \sum_{i=1}^{Nobj} \mu(F_i^k)} \quad (17)$$

The solution that obtains the maximum membership μ_D^k in the fuzzy set is chosen as the 'best' solution based on cardinal priority ranking:

$$\text{Max } \{\mu_D^k: k = 1, 2, \dots, N_S\} \quad (18)$$

5. Results and Discussions

To validate the efficiency of the proposed ORCSA, two systems where the first one is comprised of three thermal units with transmission line power losses [5] and the second consists of six units with three load cases ranging from 800 MW and 1200 MW to 1800 MW are considered [4-5]. The proposed ORCSA is coded in Matlab 7.2 programming language and run on a 1.8 GHz PC with 4 GB of Ram. The ORCSA is run twenty independent trials for each case of a set control parameter.

5.1. System I with Three Thermal Units

For the system, three dispatch cases including economic dispatch, emission dispatch and bi-objective load dispatch are carried out to determine the optimal solution. As described in 2, the optimal solution for economic dispatch is obtained by setting $w_1=1$ and $w_2=0$ and if setting $w_1=0$ and $w_2=1$, the optimal solution for the emission dispatch is found out. On the other hand, the optimal solution for the bi-objective load dispatch is more complicated to determine since a set of non-dominated solutions is first determined and then the fuzzy technique in section 4 is applied to find out the solution. For the three cases, the number of nests and the maximum number of iterations are respectively set to 12 and 45 whereas the probability P_a is

set to range from 0.1 to 0.9 with a step of 0.1 for the first two dispatch cases and then the best value of probability is fixed to determine the non-dominated solutions.

As a result, the obtained results in terms of minimum cost, average cost, maximum cost, standard deviation cost and average execution time for the economic and emission dispatch are respectively indicated in Tables 1 and 2. Obviously, the best minimum cost and emission are obtained at all values of P_a ; however, the standard deviation gives a message that the best P_a for economic dispatch is 0.9 and that for emission dispatch is in range from 0.1 to 0.9. Therefore, the best value of P_a determined is 0.9 and it is used for searching the set of non-dominated solutions. Table 3 shows the non-dominated solutions and their membership function value. Note that the solution with the highest value of membership function value is the optimal solution for bi-objective load dispatch. As observed from the table, solution 13 is the optimal solution.

The comparison of result obtained by ORCSA and other methods including Tabu Search (TS) [3], FCGA [4] and CGA [4], [NSGA-II [5], BBO [7], and CSA [11] are reported in Table 4. Clearly, the ORCSA obtains approximate or better solution than other methods because it obtains the equal or less fuel cost and emission. In addition, the ORCSA is than CSA. Other methods have not reported their execution time. Figures 1, 2 and 3 show the fitness convergence characteristic for the three cases meanwhile the Figure 4 depicts the Pareto-solution front for fuel cost and emission. Optimal solutions for the system are indicated in Table 5.

Table 1. Obtained Results for Economic Load Dispatch for System 1

p_a	Min. cost (\$/h)	Average cost (\$/h)	Max. cost(\$/h)	Std. dev. (\$/h)	CPU time (s)
0.1	8344.5927	8344.6099	8344.8341	0.0546	0.0228
0.2	8344.5927	8344.6006	8344.6607	0.0151	0.0222
0.3	8344.5927	8344.5939	8344.6022	0.0023	0.0245
0.4	8344.5927	8344.5935	8344.5993	0.0016	0.0228
0.5	8344.5927	8344.593	8344.5945	0.0005	0.0275
0.6	8344.5927	8344.5928	8344.594	0.0003	0.022
0.7	8344.5927	8344.5928	8344.5934	0.0002	0.0259
0.8	8344.5927	8344.5927	8344.5929	0.0001	0.0222
0.9	8344.5927	8344.5927	8344.5928	0	0.0175

Table 2. Obtained Results for Emission Dispatch for System 1

p_a	Min. cost (\$/h)	Average cost (\$/h)	Max. cost(\$/h)	Std. dev. (\$/h)	CPU time (s)
0.1	0.09592393	0.0959	0.09593643	0	0.0276
0.2	0.09592393	0.0959	0.09592761	0	0.0214
0.3	0.09592393	0.0959	0.09592534	0	0.0291
0.4	0.09592393	0.0959	0.09592438	0	0.0268
0.5	0.09592393	0.0959	0.09592426	0	0.0222
0.6	0.09592393	0.0959	0.09592407	0	0.0276
0.7	0.09592393	0.0959	0.0959241	0	0.0237
0.8	0.09592393	0.0959	0.09592398	0	0.0283
0.9	0.09592393	0.0959	0.09592394	0	0.0221

Table 3. Non-Dominated Solutions Obtained for System 1

Solution	w_1	Cost (\$/h)	Emission (kg/h)	μ_D^k
1	1	8344.5927	0.0987	0.0499
2	0.05	8344.5929	0.0987	0.0499
3	0.007	8344.6020	0.0986	0.0517
4	0.004	8344.6202	0.0985	0.0534
5	0.003	8344.6393	0.0984	0.0552
6	0.0017	8344.7232	0.0982	0.0585
7	0.001	8344.9222	0.0980	0.0616
8	0.0008	8345.0662	0.0978	0.0648
9	0.0006	8345.3345	0.0976	0.0677
10	0.0004	8345.9266	0.0974	0.0698
11	0.0003	8346.5450	0.0971	0.0737
12	0.0002	8347.7632	0.0968	0.0761
13	0.000125	8349.7203	0.0965	0.0767
14	0.00007	8352.7861	0.0962	0.0746
15	0.00003	8357.5460	0.0960	0.0665
16	0	8365.1157	0.0959	0.0499

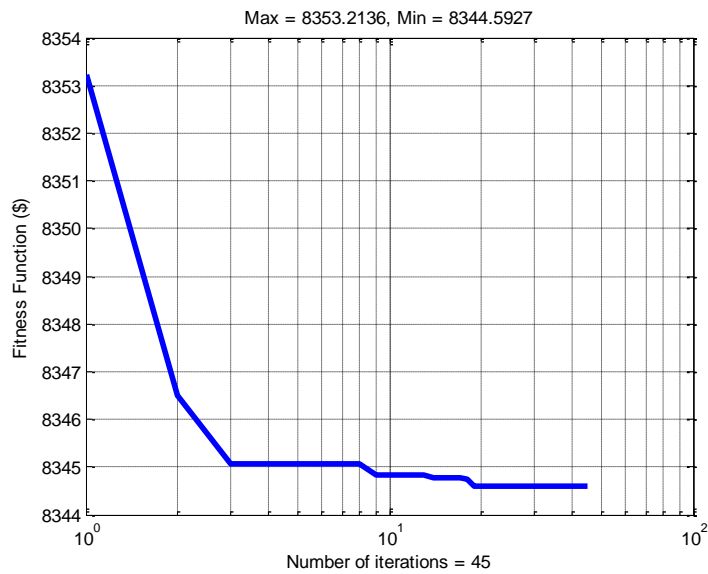


Figure 1. The Fitness Convergence Characteristic for Economic Dispatch

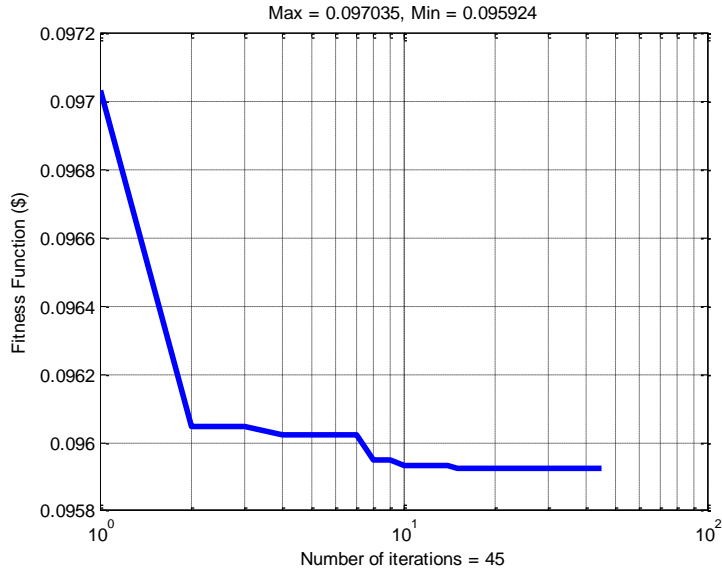


Figure 2. The Fitness Convergence Characteristic for Remission Dispatch

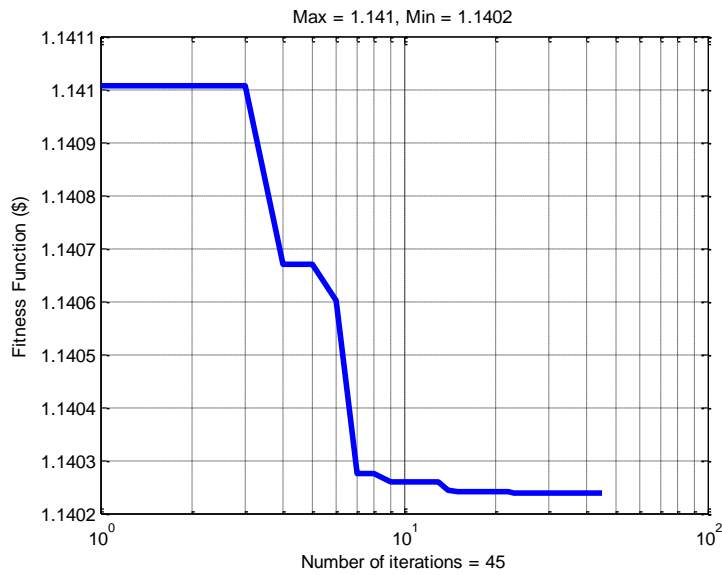


Figure 3. The Fitness Convergence Characteristic for Economic Dispatch

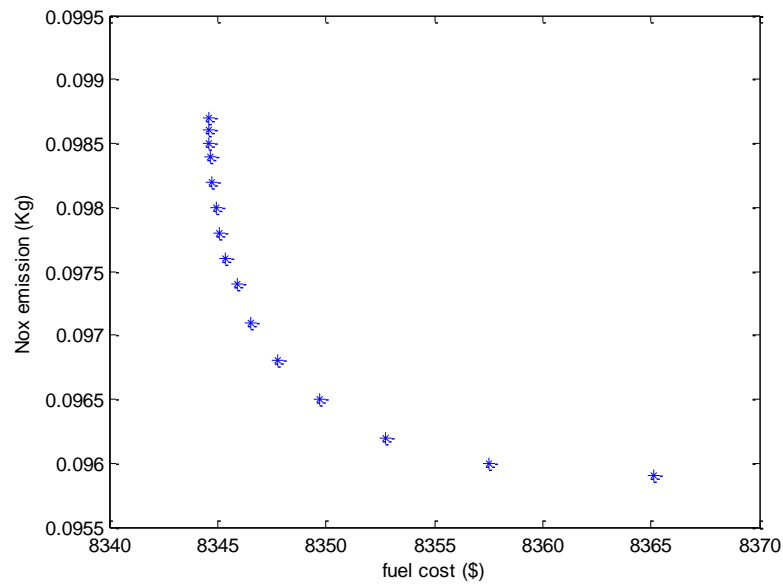


Figure 4. Pareto-Optimal Front for Fuel Cost and Emission for System I

Table 4. Result Comparisons for System 1

Dispatch	Method	Tabu Search [3]	NSGA-II [5]	BBO [7]	CSA [11]	ORCSA
Economic dispatch	Cost (\$/h)	8344.60	8344.60	8344.59	8344.59	8344.5927
	Cpu (s)	-	-	-	0.09	0.0175
Emission dispatch	Emission (kg/h)	0.0958	0.09593	0.09592	0.09592	0.095924
	Cpu (s)	-	-	-	0.07	0.0214
Economic emission dispatch	Cost (\$/h)	-	8349.72	-	8349.722	8349.7203
	Emission (kg/h)	-	0.09654	-	0.09654	0.09654
	Cpu (s)	-	-	-	0.09	0.02

Table 5. Optimal Generations for System 1

Generation (MW)	Economic dispatch	Emission dispatch	Economic emission dispatch
P ₁	435.1884	508.5316	470.8759
P ₂	299.9801	250.4805	280.8100
P ₃	130.6608	105.7343	113.6116

5.2. System II with Six Thermal Units

Similar to the manners done in section 5.1 for system 1, optimal solutions obtained by the ORCSA for the three dispatch cases for three cases of load 800 MW, 1200 MW and 1800 MW are compared to those from other methods given in Tables 6, 7 and 8. Obviously, the ORCSA obtains better cost than CGA and FCGA in [4] for all cases, and approximate cost and emission with CSA [11] for all cases.

On the other hand, OCSA is more robust than the CGA and FCGA because it spends much shorter time than these methods for searching optimal solutions. Although the ORCSA is slower than CSA for the load of 800 MW; however, it is faster than or as fast as CSA for rest of the cases. Consequently, it is concluded that the ORCSA is very efficient for solving the bi-objective load dispatch.

The optimal generations for the system are respectively given in Tables 9, 10 and 11.

Table 6. Result Comparisons for System 2 for 800 MW Load

Dispatch	Method	CGAs [4]	FCGAs [4]	CSA [11]	ORCSA
Economic dispatch	Cost (\$/h)	8232.89	8231.03	8227.1	8227.1
	Cpu (s)	14.46	5.62	0.031	0.139
Emission dispatch	Emission (kg/h)	-	-	526.3901	526.3902
	Cpu (s)	-	-	0.03	0.14
Economic emission dispatch	Cost (\$/h)	-	-	8269.5117	8333.1658
	Emission (kg/h)	-	-	568.8394	526.3902
	Cpu (s)	-	-	0.032	0.14

Table 7. Result Comparisons for System 2 for 1200 MW Load

Dispatch	Method	CGAs [4]	FCGAs [4]	CSA [11]	ORCSA
Economic dispatch	Cost (\$/h)	11493.74	11480.03	11477.09	11477.09
	Cpu (s)	17.83	7.43	0.031	0.031
Emission dispatch	Emission (kg/h)	-	-	1113.3005	1113.3005
	Cpu (s)	-	-	0.04	0.03
Economic emission dispatch	Cost (\$/h)	-	-	11517.493	11517.4923
	Emission (kg/h)	-	-	1306.6945	1306.6952
	Cpu (s)	-	-	0.032	0.031

Table 8. Result Comparisons for System 2 for 1800 MW Load

Dispatch	Method	CGAs [4]	FCGAs [4]	CSA [11]	ORCSA
Economic dispatch	Cost (\$/h)	16589.05	16585.85	16579.33	16579.33
	Cpu (s)	19.66	10.44	0.062	0.033
Emission dispatch	Emission (kg/h)	-	-	2511.9957	2511.9957
	Cpu (s)	-	-	0.03	0.03
Economic emission dispatch	Cost (\$/h)	-	-	16641.901	16641.9011
	Emission (kg/h)	-	-	2790.9434	2790.9442
	Cpu (s)	-	-	0.034	0.035

Table 9. Optimal Solution for Economic Dispatch for System 2

Generation (MW)	PD=800 (MW)	PD=1200 (MW)	PD=1800 (MW)
P ₁	100.0000	123.6392	248.0000
P ₂	100.0000	117.7755	217.7194
P ₃	50.0000	50.0002	75.1815
P ₄	305.6282	448.4074	588.0396
P ₅	122.1880	230.1075	335.5304
P ₆	122.1838	230.0703	335.5292

Table 10. Optimal Solution for Emission Dispatch for System 2

Generation (MW)	PD=800 (MW)	PD=1200 (MW)	PD=1800 (MW)
P ₁	800.0000	1200.0000	1800.0000
P ₂	100.0000	176.4610	305.5857
P ₃	100.0000	176.4614	305.5841
P ₄	117.9446	172.1752	200.0000
P ₅	140.0000	172.1754	251.3893
P ₆	171.0149	251.3638	368.7223

Table 11. Optimal Solution for Economic Emission Dispatch for System 2

Generation (MW)	PD=800 (MW)	PD=1200 (MW)	PD=1800 (MW)
P ₁	800	1200	1800
P ₂	100	159.9966	283.4604
P ₃	100	151.4681	259.3105
P ₄	53.2197	76.8531	126.2103
P ₅	200.891	308.8486	412.8611
P ₆	172.946	251.4168	359.0789

6. Conclusion

In this paper, a One Rank Cuckoo Search Algorithm has been successfully applied for solving bi-objective load dispatch problem. The ORCSA is an improved version of original CSA in which the first new solutions are newly generated directly before evaluating and ranking in addition to a bound by best solution technique for handling the inequality constraint. The performance of the ORCSA is validated by testing on two systems where large scale system with transmission line power losses is considered. The obtained result comparison have shown that the ORCSA is very efficient as applied to the bi-objective load dispatch because it can obtain better solution and faster simulation time than others.

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