

A Fuzzy based Routing Protocol for Delay Tolerant Network

Neelam Malik₁, Shailender Gupta₂ and Bharat Bhushan₃

Electronics and Communication Engineering

YMCA University of Science and Technology, Faridabad, INDIA

malikneelam.2007@gmail.com₁,shailender81@gmail.com₂,bhrts@gmail.com₃

Abstract

Delay Tolerant Network (DTN) is a wireless ad hoc network that intends to provide communication between pair of nodes in spite of having intermittent connectivity and long delays. The nodes are buffer and energy constrained. To provide communication in such scenario, a sturdy routing mechanism is needed. In this paper we propose a new routing technique based on fuzzy logic for intermittently connected network. Also an effort has been made to evaluate the performance of the proposed routing strategy in realistic environment (having obstacles) in MATLAB. The simulation results show that the performance of the network is improved using fuzzy logic based routing strategy and the results of realistic environment are quite different from idealistic environment.

Keywords: *Fuzzy Logic Controller, Realistic Environment, Routing, Rule Bas, Simulation.*

1. Introduction

The field of DTN has witnessed tremendous development [1-3] in the recent times. The network promises to provide communication between a pair of nodes in spite of frequent interruptions in route and long delays. The nodes in DTN are characterized by mobility, limited battery power and limited buffer storage. Due to this reason it is still a challenging task for designer to design a robust routing protocol which can deliver desired results even in such an environment. Naturally routing in DTN is quite different from routing in ordinary wireless network. The fundamental technique used in any routing technique to deliver the packet from source to the destination is store-carry-forward [4]. However this technique is quite difficult to implement and achieve a stable end-to-end communication path. Many researchers have designed many routing protocols for DTN [5-8] which can be broadly characterized into two categories as follows:

1.1 Deterministic Routing

Under this routing protocol [9], future movement and connection are completely known *i.e.* entire network topology is known in advance or at least is predictable accurately. Each node knows its future neighbouring nodes and their distances so that transmission can be scheduled ahead of time optimally. It is further characterized into three types[10-11] are:

1. Tree Approach
2. Space and Time Approach
3. Modified Shortest Path Approach

1.2 Stochastic Routing

In such routing protocols [9], the network behaviour is random and not known. Each node resends the received message with some probability. This protocol depends on decision as to where and when to forward the message to neighbouring nodes. The

simplest decision is to forward the packet to any neighbour within range, while other decisions are based on history, mobility pattern or any other similar information. It is further characterized into five types [12-17] are:

1. Epidemic or Random Forwarding Approach
2. Prediction or History Based Approach
 - 2.1. Per contact routing based on one hop information only.
 - 2.2. Per contact routing based on average end to end information.
3. Model based routing approach
4. Control Movement
5. Coding Based Approaches

All the above mentioned routing protocols have been proposed to increase the packet delivery ratio under given constraints. The performance of the routing protocol depends upon a number of factors *i.e.* intermittent connectivity [18], availability of network resources [19-20] like residual energy, buffer availability [21-22], mobility etc.

This paper proposes a new fuzzy logic based routing strategy that tries to maximize packet delivery ratio under the above mentioned constraints. It selects a path for communication between a source and a destination with better delay performance and lesser probability of disconnection. For this purpose a simulator is designed in MATLAB 7.0. to evaluate the performance of DTN. Also the performance of the DTN is evaluated in realistic environment [24] *i.e.* in an environment having obstacles [25] and cyclic nodes. The cyclic nodes are the ones which exhibit cyclic movement on a fixed trajectory and cyclically move in and out of a boundary of simulation region.

The rest of the paper is organized as follows: Section 2 provides literature survey and problem identification. Section 3 gives the proposed routing scheme. Section 4 gives the algorithm and simulation set up parameters. Section 5 illustrates the simulation results. Section 6 present the conclusion followed by the references.

2. Literature Survey and Problem Identification

The literature has many papers that discuss the impact of fuzzy based routing scheme on DTN performance in idealistic environment as follows:

Chenn-Jung Huang[26] proposed a fuzzy logic-based edge server selection method for heterogeneous DTN. The experimental results show that the proposed prediction based DTN routing protocol efficiently deliver messages with limited buffer space. The performance metrics used are: the data delivery ratio, average delay and transmitted bytes. The main limitation of the proposed scheme is that the server needs more storage space to record online user history log data and this might increase maintenance costs.

J.D.Mallapur[27]proposed a scheme of Minimum Spanning Tree (MST) by employing a fuzzy controller. The novelty of the proposed scheme is based on MST construction by using acceptable links computed by employing fuzzy controller that considers fuzzy input parameters: link bandwidth, link delay and link reliability. It was observed from the simulation results that the proposed scheme performs better than traditional MST while improving the packet delivery ratio and packet delays. But the main limitation of the scheme is that it does not consider the effect of the mobility of the nodes.

JadMakhlouta [28] improves the probability of delivery and latency by designing a routing protocol based upon fuzzy logic circuit *i.e* Adaptive Fuzzy Spray and Wait. Work has been done on the buffer prioritization levelusing fuzzy decision making technique which is used to classify messages into levels inside the buffer and promote the messages of high priority level during contact times. The performance of the routing in realistic scenario is not evaluated.

PayamNabhani [29] proposed a new routing scheme in order to dynamically select the relaying node from the available node list. The fuzzy logic system takes input as bandwidth, energy of the node, priority of the message and density of the network based

upon which the optimized path is selected. The simulation results of the proposed AFRON protocol show that it reduces the energy consumption per transmission with less use of resources. But the above protocol does not take into consideration the realistic scenario.

In all the above mentioned routing strategies for DTN either the effect of realistic environment or exhaustive set of parameters have not been considered. It is therefore needed to design a new routing scheme that cover maximum number of parameters and improves the performance of the network in idealistic as well as in realistic environment. In this paper an effort has been made to combine the different parameters required in the routing decision in order to design a new routing scheme based on Fuzzy Logic Controller (FLC) that improve the efficacy of the DTN. Using FLC, an Optimized path is selected that improves the performance metrics of the network in comparison to its results using Dijkstra shortest path routing protocol in DTN. Besides this the performance of the new routing strategy is also evaluated in the realistic environment. In the next section the proposed scheme is described:

3. The Proposed Routing Scheme

The new proposed routing scheme is designed using FLC[30]. Fig.1 shows the block diagram of FLC.

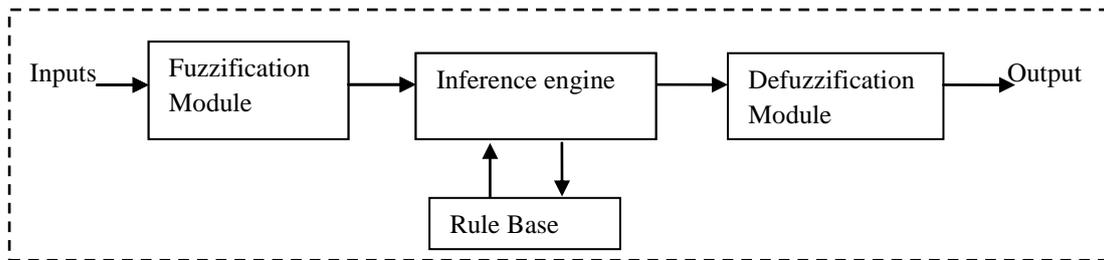


Figure 1. Block Diagram of FLC

FLC are based on expert system, which employs fuzzy logic. Fuzzy logic has two extreme values: either true(1) or false (0). FLC controls with the help of rules and collection of rules is called a rule base. Different blocks of FLC are explained as under:

Fuzzification Module: This module converts each crisp input into a fuzzy set on the domain of the input variable. The fuzzifier performs the fuzzification function that converts the inputs into suitable linguistic values which are needed in the inference engine. Different types of fuzzifier are available, some of which are: singleton fuzzifier, triangle fuzzifier, Gaussiansfuzzifier etc.

Rule Base: It contain a collection of rules in the format of ‘ IF-THEN’ where the ‘IF’ side of the rule is called antecedent and the ‘THEN’ side is called the consequent.

Inference Engine:An inference engine is a computer program that tries to derive the answer from rule base. The program used to calculate the result in inference engine is mamdani-type.

Defuzzification Module: This module converts a fuzzy set into crisp set. There are several methods available for defuzzifications: Mean-of-maxima method, centre of gravity method, modified CoG method, Height method etc.

3.1 Proposed Model:

A new fuzzy logic based routing scheme is designed using FLC. Fig.2 shows the block diagram of proposed model. The new scheme is designed based upon four input parameters *i.e.* residual energy, buffer availability, message transmission count (MTC) and fast moving nodes (FMN). These four parameters are applied as input to two FLC's FLC1 & FLC2. The output of two FLC's becomes the inputs of third FLC and gives a final output output3. Based upon the values of these four inputs for all possible paths FLC3 gives an output3. The maximized value of output3 provides us an optimized path that will ensure improved performance of the network. The three FLC used are described as follows:

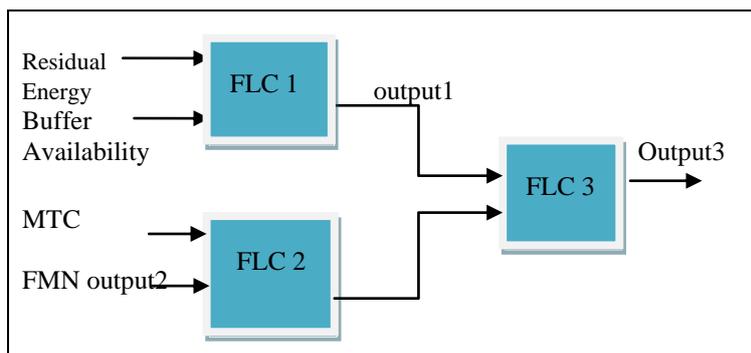


Fig.2 Block Diagram of New Fuzzy Based Routing Strategy

3.1.1 FLC1

In this FLC we provide residual energy and buffer availability of nodes as input and obtained an output output1 of a path using rule base as shown in Fig.3. The membership function for inputs of FLC1 is shown in Fig.4 and Fig.5.

3.1.2 Residual Energy

The energy is required during transmission of packet from one node to another node. Initially every node is allocated very high residual energy. If the energy level of the node is 80-100 %, it is assumed to have full capacity for communication. The node will not be a good choice to forward the packets if the energy of it falls below 4 percent. For residual energy we define five energy levels: Very Low, Low, Medium, High and Very High fuzzy set as shown in Fig.4.

3.1.3 Buffer Availability

According to our proposed scheme each node has buffer in order to store and forward the data during communication. Buffer size availability is divided into five sections Very Low, Low, Medium, High, and Very High. The path which has maximum Buffer availability for the communication is good candidate for forwarding the data between a source and a destination.

IF Buffer Availability	IF Residual Energy	THEN Output 1
Very Low	Very Low	Very Low
Very Low	Low	Very Low
Very Low	Medium	Very Low
Very Low	High	Low
Very Low	Very High	Low
Low	Very Low	Very Low

Low	Low	Low
Low	Medium	Low
Low	High	Medium
Low	Very High	Medium
Medium	Very Low	Very Low
Medium	Low	Low
Medium	Medium	Medium
Medium	High	Medium
Medium	Very High	High
High	Very Low	Low
High	Low	Medium
High	Medium	High
High	High	High
High	Very High	Very High
Very High	Very Low	Low
Very High	Low	Medium
Very High	Medium	High
Very High	High	Very High
Very High	Very High	Very High

Figure 3. Rule Base of FLC 1

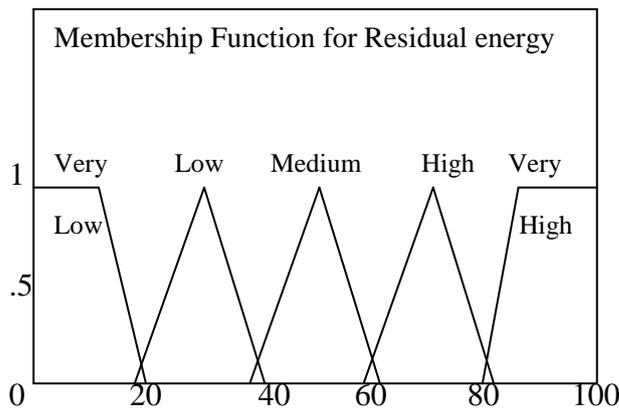


Figure 4. Membership Function for Residual Energy

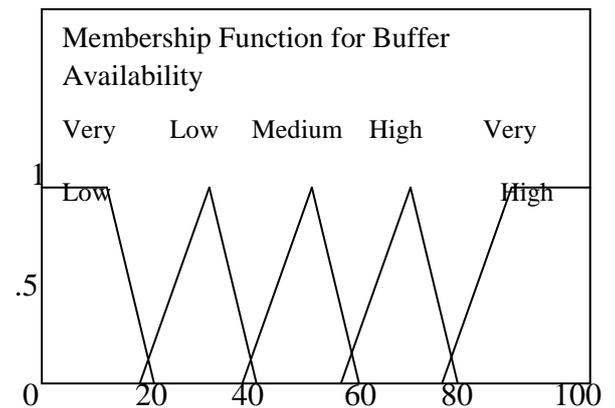


Figure 5. Membership Function for Buffer Availability

3.1.4 FLC 2

In this FLC the Message Transmission Count and Fast Moving nodes of a path are given as input. The output output2for that path is derived using rule base shown in Fig.6. The membership functions for inputs of FLC2are shown in Fig.7 andFig.8. The input parameters MTC and FMN are described below:

3.1.5 Message Transmission Count (MTC)

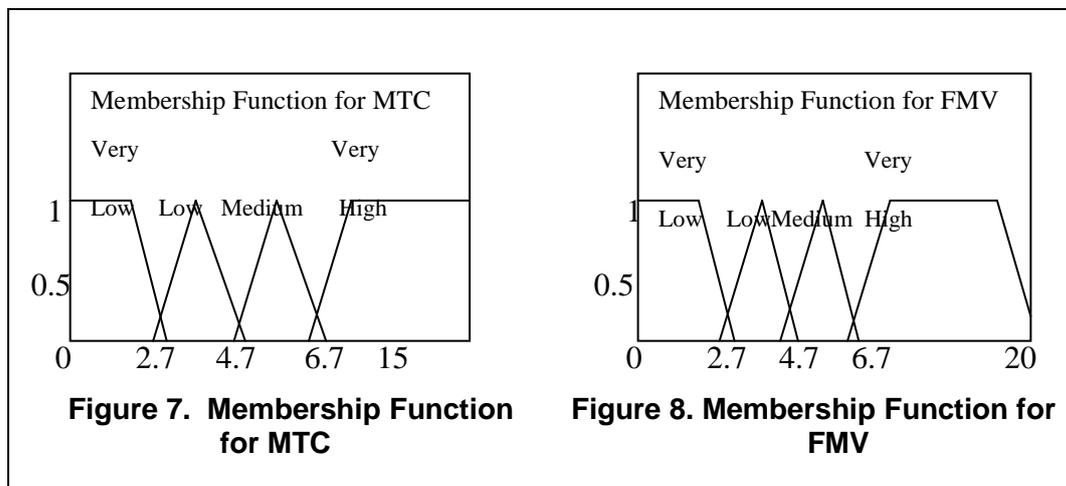
Message Transmission Count gives the number of hops from a source through which the message is encountered before reaching to its destination. The membership function of MTC is divided into four fuzzy sets: Low, Medium, High and Very High as shown in Fig.7.

3.1.6 Fast Moving Nodes (FMN)

In the proposed routing scheme, nodes are divided into two categories: slow and fast moving. Both slow and fast moving nodes may move either periodically or non-periodically in the deployed region. The nodes moving with high speed are divided into four fuzzy sets: Low, Medium, High and Very High as shown in Fig.8.

IF MTC	IF FMN	THEN Output 2
Low	Low	Very High
Low	Medium	Low
Medium	Low	High
Medium	Medium	Low
Medium	High	Low
High	Low	High
High	Medium	Medium
High	High	Low
High	Very High	Low
Very High	Low	Very High
Very High	Medium	Medium
Very High	High	Low
Very High	Very High	Low

Figure 6. Rule Base of FLC 2



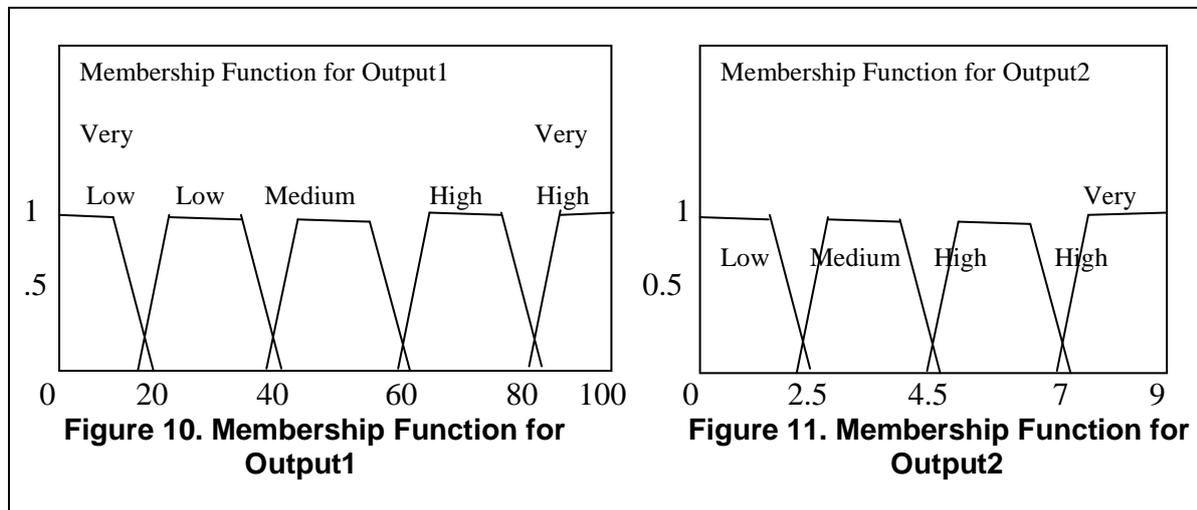
3.1.7 FLC 3

In this FLC the inputs are Output1 and Output2 of FLC1 and FLC2 respectively and give output as Output3 for that path based on rule base as shown in Fig.9. The membership function for inputs of FLC3 is shown in Fig.10 and Fig.11.

IF Output1	IF Output2	THEN Output 3
Very Low	Low	Low
Very Low	Medium	Low
Very Low	High	Low
Very Low	Very High	Medium

Low	Low	Low
Low	Medium	Low
Low	High	Low
Low	Very High	High
Medium	Low	Low
Medium	Medium	Medium
Medium	High	Medium
Medium	Very High	High
High	Low	Low
High	Medium	Medium
High	High	Medium
High	Very High	Very High
Very High	Low	Medium
Very High	Medium	Medium
Very High	High	High
Very High	Very High	Very High

Figure 9. Rule Base of FLC 3



4. Experimental Set Up

For the implementation of the proposed fuzzy logic based routing strategy for DTN a simulator was designed in MATLAB-7.0. The simulation region is of size 1500x1500 of square shape is termed as inner region and region of width 500 units is drawn around inner region termed as outer region. In the inner region forty number of nodes were distributed randomly. Dijkstra's shortest path algorithm and new fuzzy based routing strategy were used to provide communication path between a source and a destination at a given time. Fig.12 and Fig.13 show the snapshot of simulation process in idealistic and realistic environment respectively, where green lines represent the communication path using new fuzzy based routing scheme whereas lines in red colour represents path formed by using dijkstra shortest path routing. In Fig.13 green colour shaded region show the presence of obstacles in realistic scenario. Out of 40 nodes taken some nodes are designated as cyclic nodes and are represented by red dots that may moves in and out of inner periphery cyclically but never go out of outer periphery.

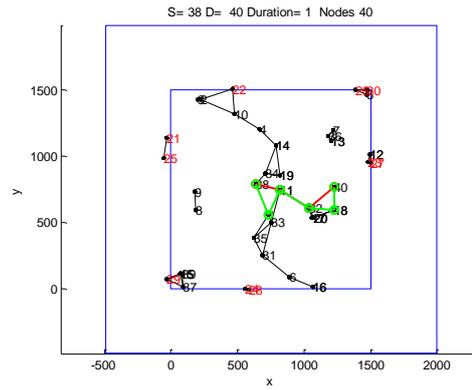


Figure 12. Snapshot of the DTN in Idealistic Environment

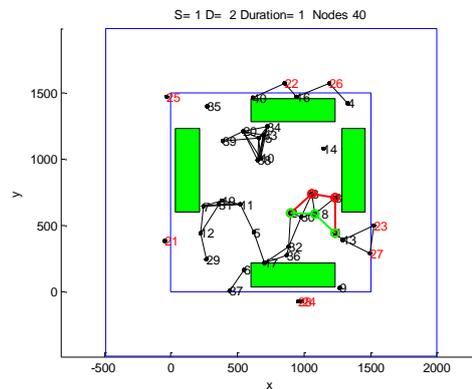


Figure 13. Snapshot of the DTN in Realistic Environment

4.1 Set up Parameters

The table 1 shows the values of set up parameters used for simulation purpose.

Table 1. Set Up Parameters

Set up parameter	Value	Set up parameter	Value
Inner region dimension	1500x1500 sq units	Speed of slow DTN nodes	1m/s
Outer region dimension	2500x2500 sq units	Routing algorithm's	Dijkstra's Shortest Path and Fuzzy based routing strategy
Numbers of nodes	40	Packet transmission interval	1sec
Transmission range	275 m	Packet Size	512 bytes
Mobility Model	Random Walk	Number of packet sent	20
Speed of fast DTN nodes	7m/s	Number of FLC	3
Placement of nodes	Random	Area of each obstacles	112500 sq units
Obstacles shape	Rectangle	Shape of periphery	Square

4.2 Algorithm

The algorithm to calculate the various performance metrics for DTN is shown in Algorithm 1. In the algorithm total forty nodes ($N=40$) were deployed and k % of nodes defined as DTN nodes [31]. To calculate the value of PoR a variable called count is used to find the total no of paths that exists between all S-D pairs. If the path exists between S-D pair, the value of *count* variable is incremented by 1. For calculating the value of average hop count using shortest path routing and new fuzzy based routing scheme the *Cum_Hop_count_shortest* and *Cum_Hop_count_fuzzy* variable is used respectively. If the path exists between pair of S-D then again check if path is intersected by an obstacle or not. If the path is not intersecting by the obstacle then the value of hop count is added to *Cum_Hop_count_shortest* and *Cum_Hop_count_fuzzy* variable using both routing scheme. This process is repeated for all combinations of S-D pairs. For calculating PDR the source sends 20 packets using procedure *send_data()* between every S-D pair and returns successfully packets received by destination. A variable called *Cum_Data_packet_shortest* and *Cum_Data_packet_fuzzy* is used to find cumulative value of packet received by destination using shortest path routing and new fuzzy based routing scheme. *Path_length_shortest* and *Path_length_fuzzy* contains the distance between source and destination thru intermediate nodes using both routing schemes. If a path is broken due to intermediate cyclic node going out of range then there is possibility of again formation of the same path. *Delay_fuzzy* and *Delay_shortest* calculate the delay between break and remake of the same path. The *average hop count*, *PoR* and *packet delivery ratio* are calculated by using formula given in algorithm.

Algorithm 4.2: To Calculate Various Performance Metrics

```

Total Nodes  $N = 40$ ;  $count = Cum\_Data\_Packets = Cum\_hop\_count = 0$ ;
Delay_fuzzy = Delay_shortest = 0;

for  $i = 1$  to  $N - 1$ 
    for  $j = i + 1$  to  $N$ 
        If (S-D path exists)
            For packet = 1:20
                If (S-D path break)
                    Delay_fuzzy = delay_fuzzy + 1;
                    Delay_shortest = delay_shortest + 1;
                Continue
            else
                Cum_DataPacket_fuzzy = Cum_DataPacket_fuzzy + Send data( );
                Cum_DataPacket_shortest = Cum_DataPacket_shortest + Send data( );
                Cum_hop_count_fuzzy = Cum_hop_count_fuzzy + Hop_count_path1;
                Cum_hop_count_shortest = Cum_hop_count_shortest + Hop_count_path2;
                Count++
            end
        end
    end
end

PDR_fuzzy =  $2 * Cum\_DataPacket\_fuzzy / N / (N - 1)$ ;
PDR_shortest =  $2 * Cum\_DataPacket\_shortest / N / (N - 1)$ ;
PoR =  $2 * Count / N / (N - 1)$ ;
Hop Count_fuzzy =  $2 * Cum\_hop\_count\_fuzzy / N / (N - 1)$ ;
Hop Count_shortest =  $2 * Cum\_hop\_count\_shortest / N / (N - 1)$ ;

```

4.3 Performance Metrics

The following parameters are used as performance metrics for DTN:

4.3.1 Packet delivery ratio (PDR)[32]:defined as the number of packets received by the destination to the total number of packets sent by the source.

4.3.2 Hop count[33]:defined as the number of intermediate nodes required to establish the path from source to destination.

4.3.3 Probability of reachability (PoR)[34]:defined as fraction of possible reachable routes to all possible routes that may physically exist between every pair of source and destination.

4.3.4 Delay[35]:defined as the time duration in which a broken path is reformed.It is an interval between a path broken and again reformation of the same path.

5. Simulation Results

5.1 Impact on Packet Delivery Ratio (PDR)

Fig.14 shows the impact on PDR using proposed routing and shortest path routing in both idealistic and realistic environment. The following inference can be drawn from the graph:

- The proposed strategy increases the value of PDR in comparison to its value using shortest path routing protocol using both idealistic and realistic scenario.It is due to reason that the optimized path using fuzzy method has lesser probability of disconnection in comparison to the shortest path.
- As the percentage of cyclic nodes increases the value of PDR decreases continuously.
- The presence of obstacles results in decrease in value of PDR using either strategy.

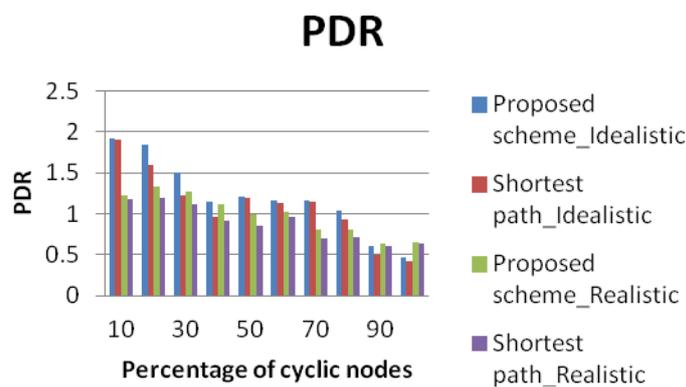


Figure 14. Impact on PDR

5.2 Impact on Hop Count

Fig.15 shows the comparison of impact of using proposed routing scheme and shortest path routing scheme on hop count in both idealistic and realistic environment. The following inference can be made from the graph:

- The value of hop count in the fuzzy based strategy is larger than the value of hop count for shortest path routing strategy in the same scenario (idealistic or

realistic).The reason for the same is that the path length of the optimized path is larger in comparison to the shortest path. The other reason may be that the optimized path contains large number of slow moving nodes than the shortest path that reduces the chance of disconnection of optimized path.

- As the percentage of cyclic nodes increases the value of hop count decreases.
- The presence of obstacles in realistic environment results in increase of value of hop count because obstacle results in increases in path length.

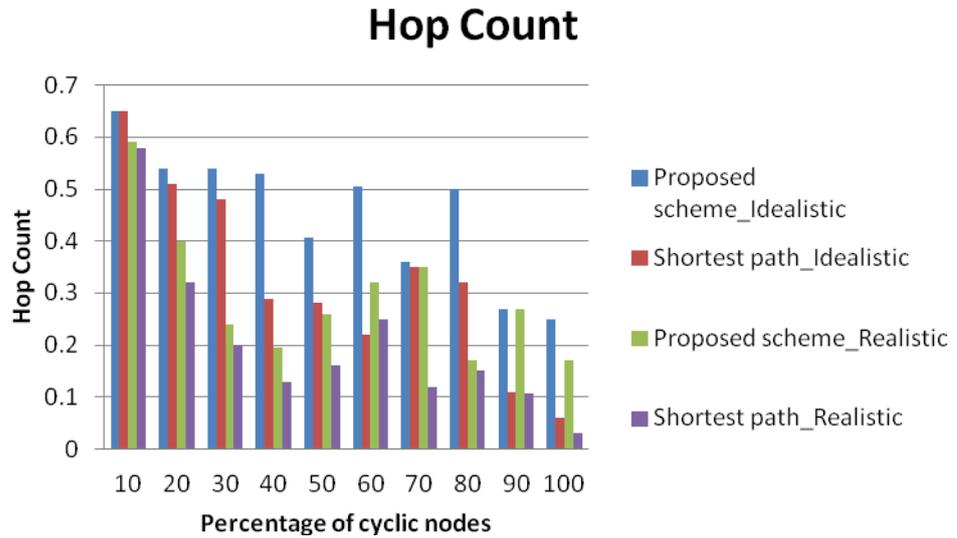


Figure 15. Impact on Hop Count

5.3 Impact on Probability of Reachability (PoR)

Fig.16 shows the impact on PoR using proposed routing scheme and shortest path routing scheme in both idealistic and realistic environments. The following inference can be made from the graph:

- The value of PoR in idealistic scenario is higher than the value of PoR in realistic scenario. This is due to the hindrance provided by the obstacles to the signal between neighbouring nodes. Hence lesser number of reachable routes is formed in realistic environment compared to its value in the idealistic environment.
- The value of PoR decreases as the percentage of cyclic nodes increases. With increase in percentage of cyclic nodes, more number of nodes may move out of inner periphery that may lead to disconnection of the path.

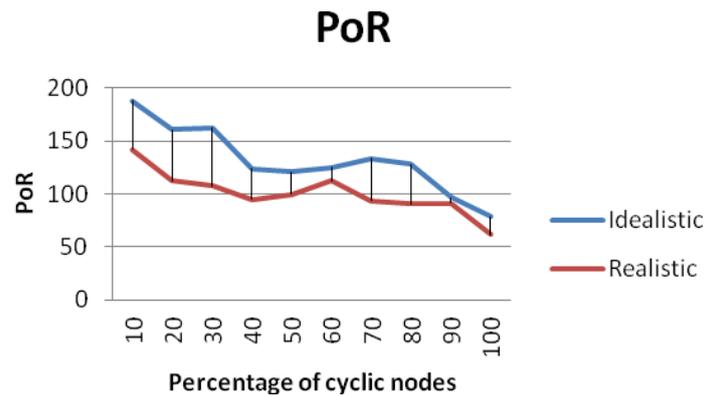


Figure 16. Impact on PoR

5.4 Impact on Delay

Fig.17 shows the impact on delay introduced during communication using proposed scheme and shortest path scheme in both idealistic and realistic environments. The following inference can be made from the graph:

- As the percentage of cyclic node increases delay in the communication increases. This is due to the fact that the possibility of reformation of the broken path due to the presence of cyclic nodes increases.
- Using proposed fuzzy logic strategy, the value of delay introduced in the communication path is lesser than the delay introduced using shortest path routing strategy. This shows that using shortest path routing there is lesser number of completion of data transfer takes place in comparison to proposed fuzzy logic based strategy.
- The value of delay in realistic environment is more than its value in idealistic environment. This is due to presence of obstacles. More number of paths are likely to break and there is more likelihood of reformation of the broken path that increases the delay in data transmission.

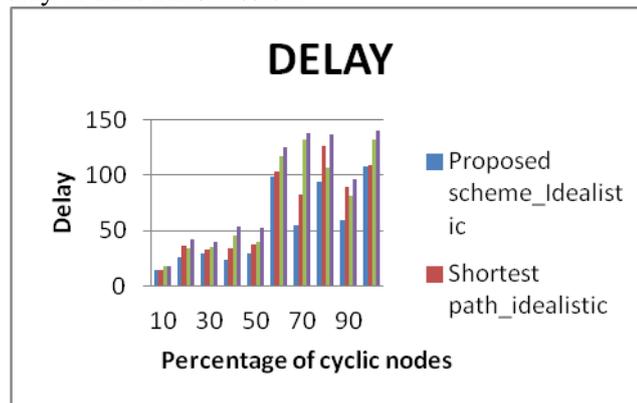


Fig.17 Impact on Delay

6. Conclusion

In this paper an effort has been made to design a new routing scheme based on fuzzy logic for DTN and compare its performance with shortest path routing technique in an idealistic environment and realistic environment. The following inference may be drawn from the results:

- The performance metrics of DTN using proposed fuzzy logic based strategy improves the performance of the network over its performance using shortest path routing strategy.
- The performance of the network degrades gradually due to the presence of the obstacles using both routing strategies. This shows that the idealistic results cannot be used for practical applications.
- The network performance decreases as the percentage of cyclic nodes increase using both strategies in idealistic and realistic scenarios.

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Authors



Neelam Malik
Assistant Professor
NIT kurukshetra, kurukshetra