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Analysis of Mutual Language Intelligibility of the Programming Tool Used in Robot Programming Learning

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Abstract

In the Republic of Korea, several policies and studies are underway to organize a software curriculum into a regular course. In this study, we compared and analyzed several programming tools available in the robot programming learning activities of the software curriculum. Programming tools utilized in this study were MSRDS VPL and App Inventor and these were performed in a class by utilizing robots. As students can easily learn the foreign language similar to their mother tongue, this study examined how easily students were able to learn another programming language with a similar interface.

Keywords: *Software Education, MSRDS, App Inventor, Block Type Programming*

1. Introduction

The 21st century we live has entered a knowledge-oriented society due to the development of ICT skills. The developed various information-based technologies and application technologies have applied to many fields [1], and the development of the information communication technology such as wireless internet, mobile internet devices and the Internet of Things has given an impact on an educational environment. Such a society pursues the human who is not standardized by monolithic education but thinking creatively about what is happening in the world and able to actively respond to changes in a given environment. Therefore, new education which can cultivate a creative problem-solving ability on the basis of creativity is required, not the former education doing such as rote learning and cramming education [3]. In the Republic of Korea, the information curriculum of elementary and secondary education was renamed as the software curriculum, and the curriculum was revised to teach software based on Computational Thinking. Universities are seeking changes for carrying out software education for all students. In particular, Ministry of Science, ICT and Future Planning is working for training software-talented individuals by supporting 11 billion won for six years as a supporting business of software-oriented university at the national level [4]. In this study, we compared MSRDS VPL and App Inventor with C language in class and we used robots as educational materials. This study tried to find out the mutual language intelligibility among languages.

2. Related Research

2.1. Preceding Research

C. J. Park (2015) analyzed the relationship among the abstract thinking, language intimacy, and study achievement about the understanding of C and Scratch program. Park

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showed that C and Scratch were main languages which the students of the study had experienced before, and the language intimacy of Java or Visual Basic affected students' abstract thinking skills positively.

S. W. Seo (2010) compared the text-based programming languages with the visual-based programming languages. Seo concluded that the text-based programming languages affected the improving thinking ability of science of information more meaningfully than the visual-based programming languages [6].

2.2. Programming Tools

This study has investigated the keyword, mutual language intelligibility among several programming tools. It is easy to learn a foreign language which is very similar mutually. MSRDS (MicroSoft Robotics Developer Studio) is developing tools and an environment that help to facilitate the development of various robotic applications if professional workers or ordinary people have general knowledge of robot programming. Figure 1 and Figure 2 shows a programming result as if there were robot equipment [7].

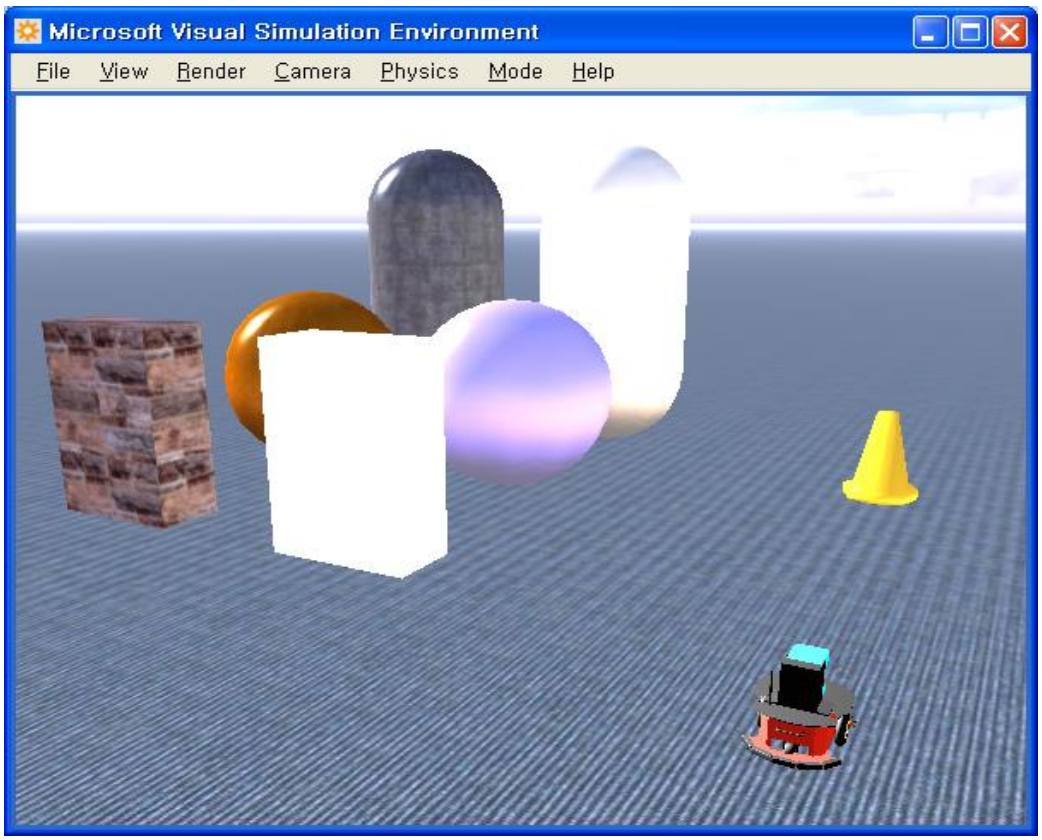

Figure 1. Robotics Simulation (Keyboard Control)

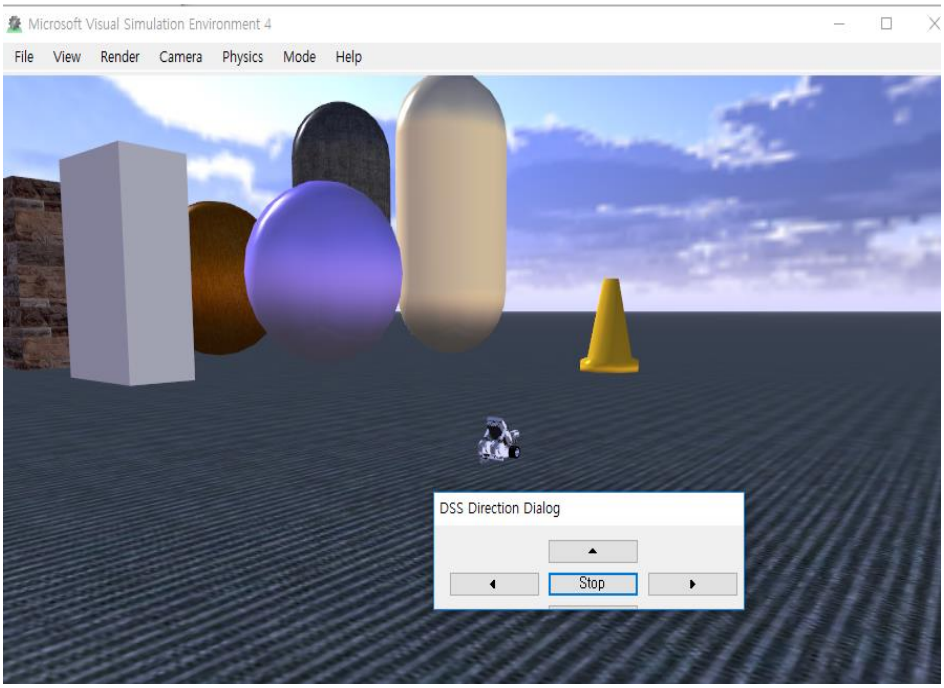

Figure 2. Robotics Simulation (Direction Dialog Control)

VPL (Visual Programming Language) helps people do programming by connecting lines between icon-based shapes named Activity as shown in Figure 3 and Figure 4. Also, VPL helps easily to understand the basic concepts of programming and very usefully to grasp the principles of the programming.

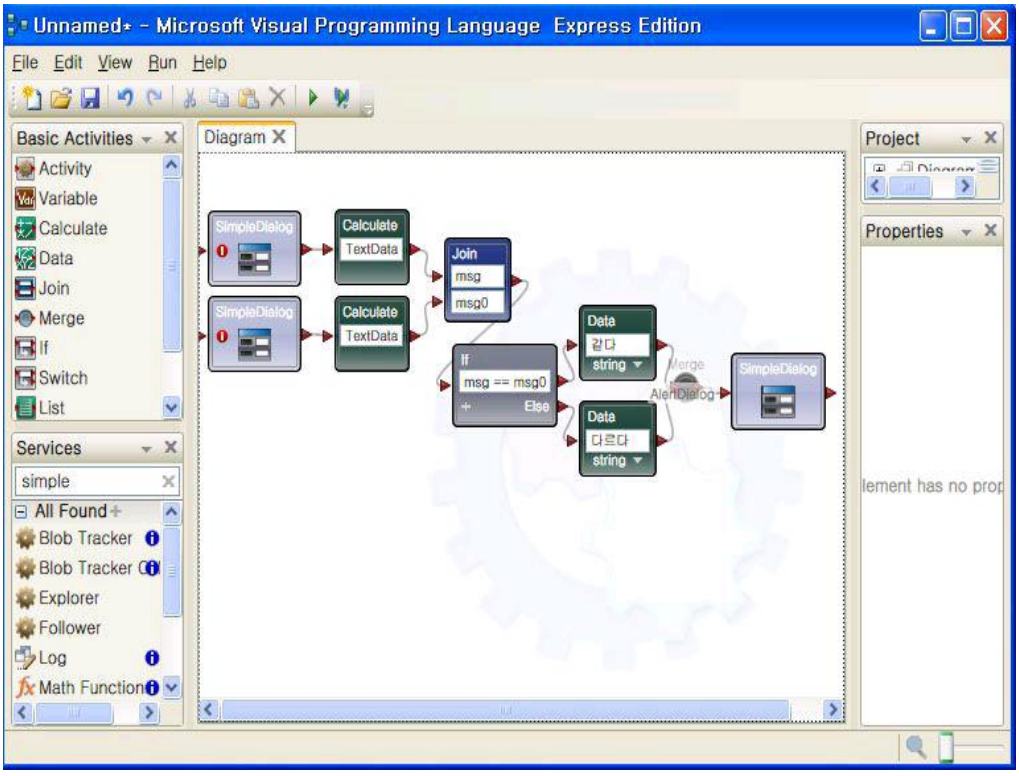

Figure 3. Source Code Programming by VPL (Level Low)

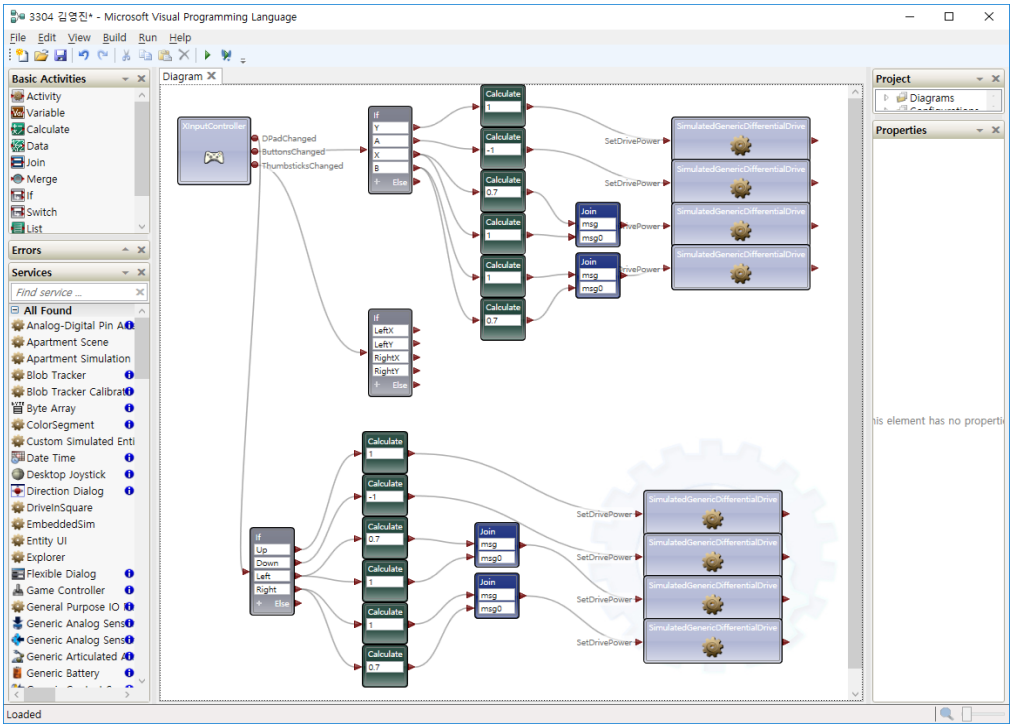

Figure 4. Source Code Programming by VPL (Level High)

App Inventor was a project to provide a developing environment to replace the existing programming languages in order to make it easy to develop applications that run on Android operating system [8]. As Figure 5 and Figure 6, App Inventor helps designing like an environment similar to smart phones, can take advantage of the sensor of smart phones, and can program with blocks as shown in Figure 7 and Figure 8.

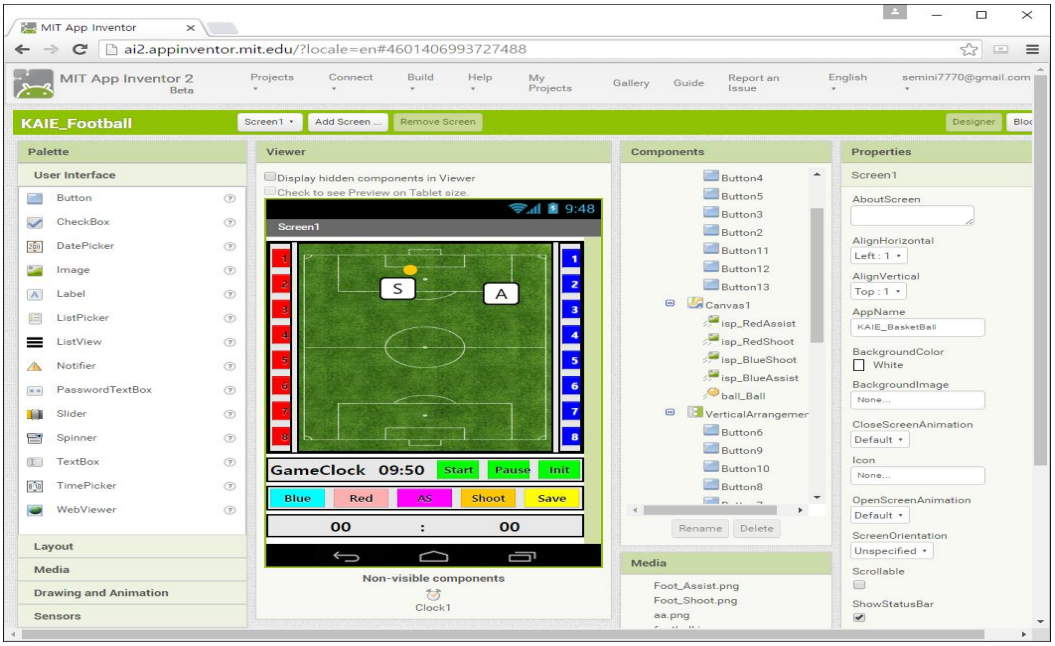

Figure 5. Design Screen of App Inventor (Level Low)

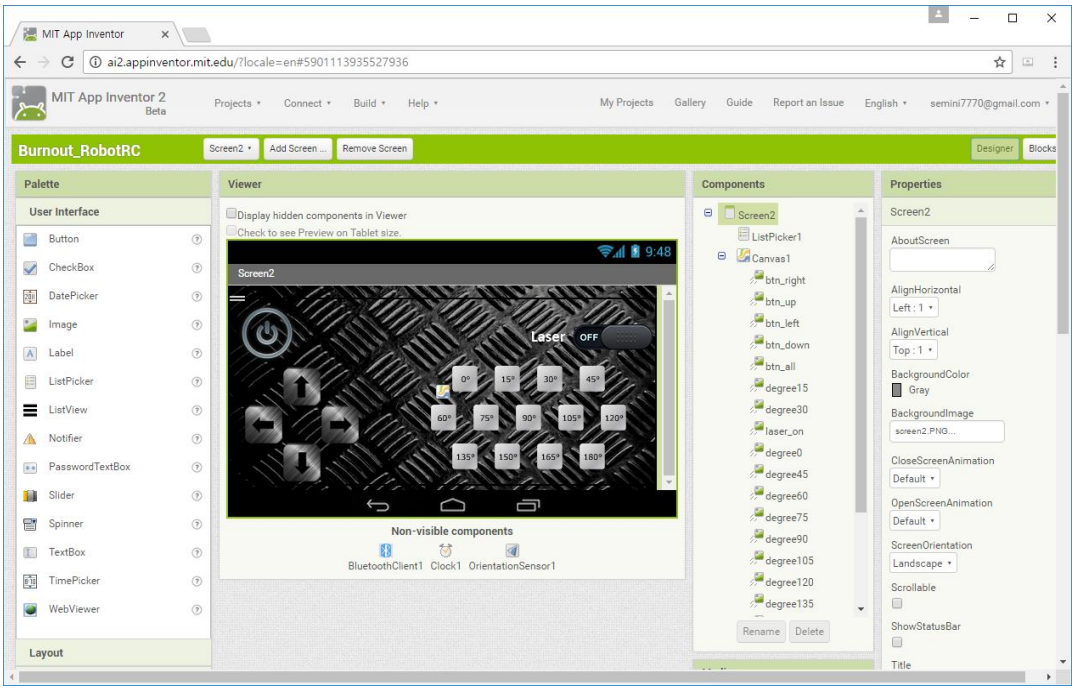

Figure 6. Design Screen of App Inventor (Level High)

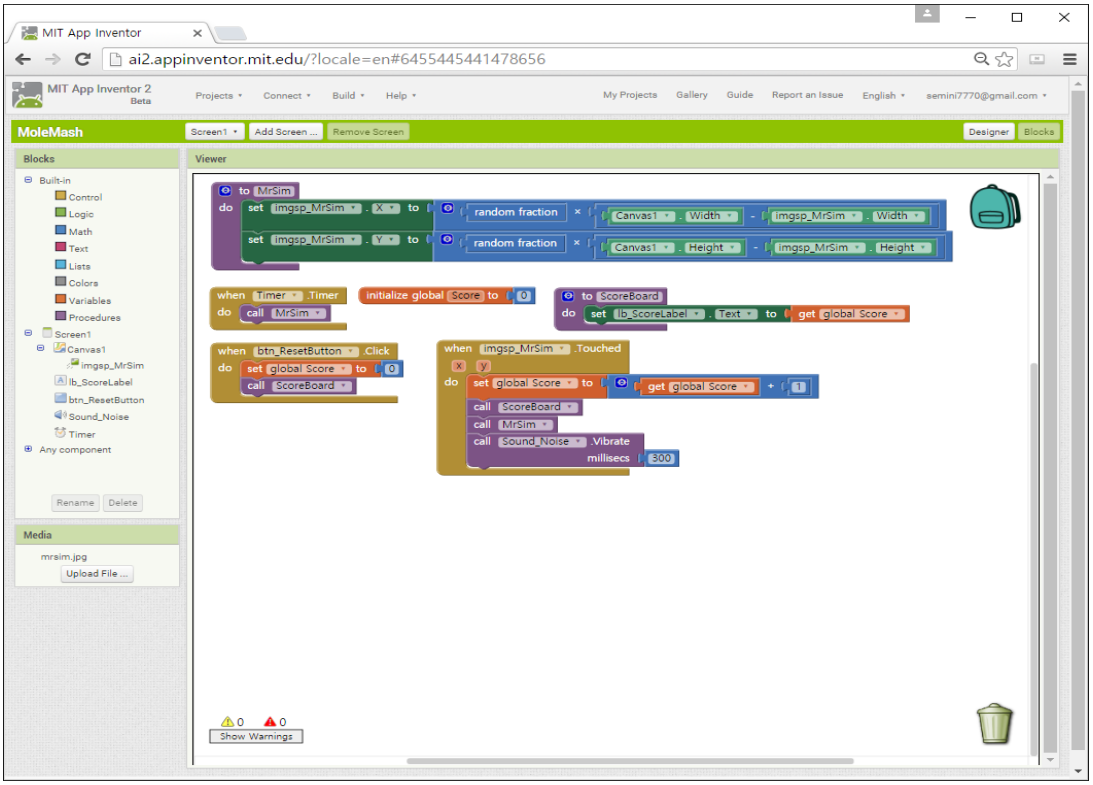

Figure 7. Block Programming Screen of App Inventor (Level Low)

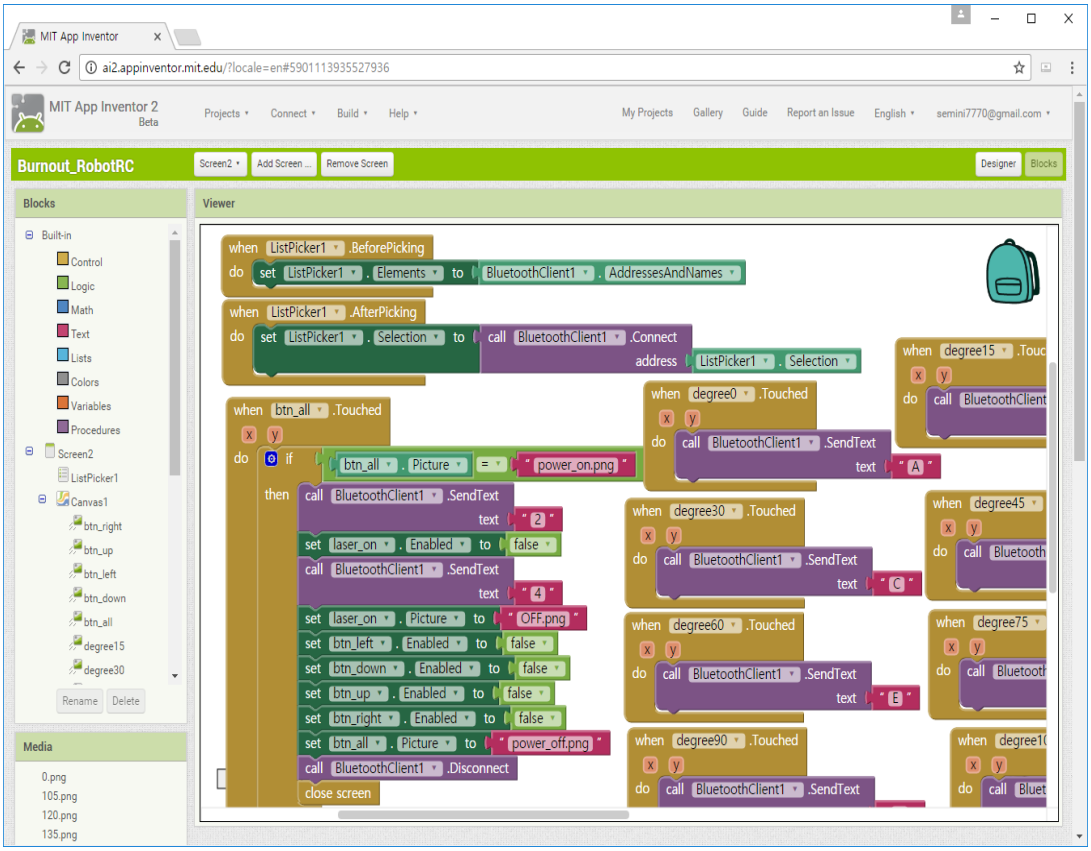

Figure 8. Block Programming Screen of App Inventor (Level High)

3. Main Title

3.1. Subject of Study

The subjects of this study were composed of 20 second year students of A technical high school and 20 second year students of B technical high school. All of the subjects were learning C language in other classes in the semester. The students of A technical high school learned App Inventor first and MSRDS later. The students of B technical high school learned MSRDS VPL first and then App Inventor. Their performances were evaluated every week with a given mission. In addition, the results of programming were commonly confirmed by a LEGO Mindstorm robot.

2.2. Lesson Plan

The Subjects were taught following the lesson plan like Table 1 and Table 2. “A course” was the plan before a mid-term examination, and “B course” was the plan before a final examination. In school A and B, “A course” and “B course” proceeded only by changing the order.

Table 1. Lesson Plan (A Course)

A Course	Contents
1st week	MSRDS VPL basics
2nd week	basic Activity
3rd week	robotic simulation
4th week	variable
5th week	operator
6th week	input-output statement
7th week	control statement
8th week	Mid-term exam

Table 2. Lesson Plan (B Course)

B Course	Contents
9th week	App Inventor basics
10th week	design
11th week	sensor utilization
12th week	variable
13th week	operator
14th week	input-output statement
15th week	control statement
16th week	Final exam

4. Robot Programming Application in Classes and Result Analysis

In this study, the units which had no matching points between both programming tools were excluded in the analysis. However, the performance assessment scores of students were measured for learning. The important result of this study was the part with similarities of the two programming languages and with the direct relationship of programming Logic. This corresponds to variables, operators, input-output statements, and control statements. The learning results of units would be analyzed as shown in Table 3 and Table 4.

The Students of A technical high school learned App Inventor first and then MSRDS. In general, the understanding of App Inventor has an average of 4% or higher. Because App Inventor was the programing language mostly similar to the interface of Scratch and Entry which was in recent trend, App Inventor might be familiar to the eyes of students and influenced mutual language intelligibility. Particularly in the section of variable of MSRDS VPL, there was the most gap, 4% deviation of performance assessment because the procedure for setting variables in MSRDS VPL was more difficult than App Inventor. Therefore, if the use of programming language tools is difficult, the mutual language intelligibility will be lower.

The students of B school learned MSRDS VPL first and then learned App Inventor. In general, the understanding of App Inventor was averaging 6% or higher. Like A school students, there was the most deviation (3%) in the variable section. However, A school's average percentage of mission performance was 87% and B school's 81%. It can be said that A school's students who learned App Inventor first accepted another language more easily than B school's students who learned MSRDS first, and A school's students had a higher mutual language intelligibility than B school's students.

Table 3. Lesson Result of A School

Week	A School mission performer/total (percentage)
MSRDS VPL basics	25/25 (100%)
basic Activity	24/25 (96%)
robotic simulation	24/25 (96%)
variable	20/25 (80%)
operator	23/25 (92%)
input-output statement	20/25 (80%)
control statement	21/25 (84%)
App Inventor basics	25/25 (100%)
design	24/25 (96%)
sensor utilization	20/25 (80%)
variable	24/25 (96%)
operator	23/25 (92%)
input-output statement	21/25 (84%)
control statement	21/25 (84%)

Table 4. Lesson Result of B School

Week	B School mission performer/total (percentage)
MSRDS VPL basics	24/25 (96%)
basic Activity	23/25 (92%)
robotic simulation	22/25 (88%)
variable	19/25 (80%)
operator	20/25 (80%)

input-output statement	20/25 (76%)
control statement	19/25 (76%)
App Inventor basics	24/25 (96%)
design	24/25 (92%)
sensor utilization	20/25 (80%)
variable	22/25 (88%)
operator	21/25 (84%)
input-output statement	20/25 (80%)
control statement	21/25 (84%)

4. Conclusions and Recommendations

This paper studied the mutual language intelligibility between two visual programming languages and following results was obtained. First, because of App Inventor's similarity of structure to Scratch, App Inventer has an advantage in the mutual language intelligibility rather than MSRDS VPL. Second, a somewhat complicated procedure of setting like variables setting in SRDS VPL can affect the mutual language intelligibility. Third, after learning the programming language with a higher mutual language intelligibility than other existing programming languages, the learning can be helpful to study next programming languages. Although this study compared languages among icon or block-based programming languages, subsequent studies need to investigate the mutual language intelligibility of the existing C language, Basic, Java, etc.

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